# Vladimir Matveev Jena (Germany)

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 $www.minet.uni-jena.de/{\sim}matveev/$ 

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- theory of geodesically equivalent metrics and Levi-Civita Painlevé Eisenhart Weyl Thomas Douglas Hall Rashevskii Solodovnikov Yamauchi Aminova Venzi Mikes Shandra
- ▶ theory of quadratically integrable Hamiltonian systems and separations of variables

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We apply methods of one in the other and obtain the announced classical problems

#### **Definitions**

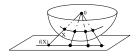
#### Definitions

1. Two metrics (on one manifold) are geodesically equivalent if they have the same unparametrized geodesics

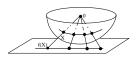
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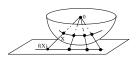
1. Two metrics (on one manifold) are geodesically equivalent if they have the same unparametrized geodesics

2. A vector field is projective w.r.t. a metric, if its flow takes (unparametrized) geodesics to geodesics.

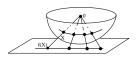


Radial projection  $f:S^2 o \mathbb{R}^2$ 

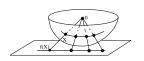




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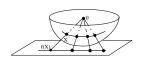


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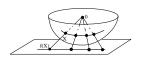
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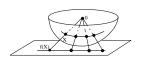
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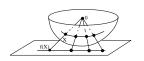
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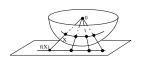


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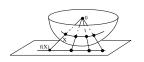


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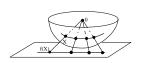


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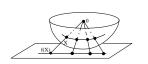
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Pseudo-Riemannian case: Two more series of normal forms: Bolsinov, Pucacco,  $M{\sim}~2008$ 

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There is no problem to introduce potential energy in the picture (Bolsinov, M $\sim 2003/$  Crampin, Scarlet 2003/ Benenti 2004 / Kruglikov, M $\sim 2006$ ; Bolsinov, Pucacco, M $\sim 2008$ )

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Since the forms  $\sigma$ ,  $m^*\bar{\sigma}$  are preserved by the flow, a function constructed invariantly by using these forms must automatically be an integral.

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The example of Beltrami gives us a pair of geodesically equivalent metrics. If we apply the above Theorem to it for functions F(x) = x and  $F(x) = x^2$ , we get the metrics of the ellipsoid and of the Poisson spheres.

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**Repeating Def:** A vector field is projective (w.r.t. a metric), if its flow takes unparameterized geodesics to geodesics.

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$$\epsilon_1 e^{(b+2)\times} dx^2 + \epsilon_2 b e^{b\times} dy^2$$
, where  $b \in \mathbb{R} \setminus \{-2, 0, 1\}$  and  $\epsilon_i \in \{-1, 1\}$ 

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$$a\left(\epsilon_1 \frac{e^{(b+2)\times}dx^2}{(e^{b\times}+\epsilon_2)^2} + \frac{e^{b\times}dy^2}{e^{b\times}+\epsilon_2}\right)$$
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$$a\left(\frac{e^{2x}dx^2}{x^2} + \epsilon \frac{dy^2}{x}\right)$$
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$$a\left(\frac{dx^2}{(cx+2x^2+\epsilon_2)^2x}+\epsilon_1\frac{xdy^2}{cx+2x^2+\epsilon_2}\right)$$
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I proved **Lichnerowicz-Obata-Solodovnikov Conjecture (50th):** Let a complete Riemannian manifold (of dim  $\geq 2$ ) admit a complete projective vector field. Then, the manifold is covered by the round sphere, or the vector field is affine.

It is hard to relax the assumptions

History of L-O-S conjecture:

France	Japan	Soviet Union
(Lichnerowicz)	(Yano, Obata, Tanno)	(Raschewskii)
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Pseudo-Riemannian case was considered: Venzi 85, Barnes 93, Hall 95.



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(Alternatively: Tracefreepartof( $\hat{\Gamma} - \Gamma$ ) = 0).

Then, on the level of equations

$$\left[\frac{\partial}{\partial k}g_{ij} - g_{i\alpha}\Gamma^{\alpha}_{kj} - g_{j\alpha}\Gamma^{\alpha}_{ki}\right] - \Upsilon_{i}g_{kj} - \Upsilon_{j}g_{ki} = 0$$

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 on unknowns  $g_{ij}$  and  $\Upsilon_i$ .



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on unknowns  $g_{ij}$  and  $\Upsilon_{i}$ . The system is nonlinear and Contains artificial unknown  $\Upsilon$ 

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$$\nabla_{a}\sigma^{bc} = \underbrace{\frac{\partial}{\partial x^{a}}\sigma^{bc} + \Gamma^{b}_{ad}\sigma^{dc} + \Gamma^{c}_{da}\sigma^{bd}}_{} - \underbrace{\frac{2}{n+1}\Gamma^{d}_{da}\sigma^{bc}}_{}$$

Usual covariant derivative

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#### Advantages:

1. It is a LINEAR PDE-system of the first order.

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#### Advantages:

- 1. It is a LINEAR PDE-system of the first order.
- 2. The system does not depend on the choice of  $\Gamma$  within a projective class.



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#### Advantages:

- 1. It is a LINEAR PDE-system of the first order.
- 2. The system does not depend on the choice of  $\Gamma$  within a projective class. (short tensor calculations)



**Def:** Projective connection of an affine connection  $\Gamma$  is

$$y_{xx} = -\Gamma_{11}^{2} + (\Gamma_{11}^{1} - 2\Gamma_{12}^{2})y_{x} + (-\Gamma_{22}^{2} + 2\Gamma_{12}^{1})(y_{x})^{2} + \Gamma_{22}^{1}(y_{x})^{3}$$

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It is easy to describe such projective connections (Lie, Cartan, Tresse):

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It is easy to describe such projective connections (Lie, Cartan, Tresse): in a certain coordinate system they are as follows:  $(A,B,C,D\in\mathbb{R}$ )  $y_{xx}=e^xA+By_x+Ce^{-x}(y_x)^2+De^{-2x}(y_x)^3$ .

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Lie Problem is equivalent to "Which of them come from a metric"

Theorem (R. Liouville 1889 – Eastwood/ M $\sim$  2007 – Bryant/Manno/M $\sim$  2007)

Theorem (R. Liouville 1889 – Eastwood/  $M\sim 2007$ – Bryant/Manno/ $M\sim 2007$ ) A 2-dimensional metric g has a given projective connection

$$y_{xx} = K_0 + K_1 y_x + K_2 (y_x)^2 + K_3 (y_x)^3$$

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iff the entries of the matrix  $a \stackrel{\text{def}}{=} (det(g))^{-2/3} g$  satisfy a system of 4 linear PDE of first order.

$$y_{xx} = K_0 + K_1 y_x + K_2 (y_x)^2 + K_3 (y_x)^3$$

iff the entries of the matrix  $a \stackrel{\text{def}}{=} (det(g))^{-2/3} g$  satisfy a system of 4 linear PDE of first order.

$$\begin{cases} \frac{\partial a_{11}}{\partial x} + 2 K_0 a_{12} - 2/3 K_1 a_{11} &= 0\\ 2 \frac{\partial a_{12}}{\partial x} + \frac{\partial a_{11}}{\partial y} + 2 K_0 a_{22} + 2/3 K_1 a_{12} - 4/3 K_2 a_{11} &= 0\\ \frac{\partial a_{22}}{\partial x} + 2 \frac{\partial a_{12}}{\partial y} + 4/3 K_1 a_{22} - 2/3 K_2 a_{12} - 2 K_3 a_{11} &= 0\\ \frac{\partial a_{22}}{\partial y} + 2/3 K_2 a_{22} - 2 K_3 a_{12} &= 0 \end{cases}$$

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Thus, the projective connection came from a metric iff this system of PDE has a nontrivial solution.

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Thus, the projective connection came from a metric iff this system of PDE has a nontrivial solution.

To solve the Lie problem = to determine constants A, B, C, D

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Thus, the projective connection came from a metric iff this system of PDE has a nontrivial solution.

To solve the Lie problem = to determine constants A, B, C, D such that the system above with

$$K_0 = e^x A$$
,  $K_1 = B$ ,  $K_2 = Ce^{-x}$ ,  $K_3 = De^{-2x}$ 

$$y_{xx} = K_0 + K_1 y_x + K_2 (y_x)^2 + K_3 (y_x)^3$$

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Thus, the projective connection came from a metric iff this system of PDE has a nontrivial solution.

To solve the Lie problem = to determine constants A, B, C, D such that the system above with

$$K_0 = e^x A$$
,  $K_1 = B$ ,  $K_2 = Ce^{-x}$ ,  $K_3 = De^{-2x}$ 

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#### This is an algorithmically-solvable problem

(if we can differentiate, multiply and add).



Differentiate every equation of the above system w.r.t. xx, xy, yy

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Now, let us produce new linear PDE's of the second order

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Now, let us produce new linear PDE's of the second order Step 1: Take  $\frac{\partial f_{ijkrm}}{\partial x_s} - \frac{\partial f_{ijkrs}}{\partial x_m}$  and substitute (\*) inside.

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Step 1: Take  $\frac{\partial f_{ijkrm}}{\partial x_c} - \frac{\partial f_{ijkrs}}{\partial x_m}$  and substitute (\*) inside.

Step 2: Differentiate the obtained equations by  $x_{\alpha}$  and substitute (\*) inside.

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Then, 18 minus the rank of the systems of equation we obtained is the dimension of the space of solutions of (\*), i.e. is the dimension of the space of the metrics corresponding to the above projective connection.

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### Theorem (Bryant, Manno, M $\sim$ ).

 $y_{xx} = e^x A + By_x + Ce^{-x}(y_x)^2 + De^{-2x}(y_x)^3$  comes from a metric iff A = C = 0 (may be after a coordinate change)

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Of cause, we also have a hand-written proof.

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Then, for every solution  $\sigma \in \sigma$ , then  $L_{\nu}\sigma$  is also a solution. Thus,  $L_{\nu}$  is a linear mapping  $: \sigma \longrightarrow \sigma$ .

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In the left case

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In the left case there exists a solution s.t.  $L_{\rm v}\sigma=\alpha\sigma$ 

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In the left case there exists a solution s.t.  $L_v\sigma=\alpha\sigma$  implying v is homothety vector for g which is impossible for closed manifolds.

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#### Thanks a lot!!!

