

On the Degree of Geodesic Mobility for Riemannian Metrics

V. A. Kiosak, V. S. Matveev*, J. Mikeš, and I. G. Shandra

Received October 28, 2008

DOI: 10.1134/S0001434610030375

Key words: *degree of geodesic mobility, Riemannian metric, geodesically equivalent metrics, concircular covector field, space of nonconstant curvature, Ricci tensor, Weyl curvature.*

Two metrics g and \bar{g} on the same manifold M are said to be *geodesically equivalent* if any geodesic of the metric g can be parameterized so as to become a geodesic of \bar{g} . As is known [1], there is a one-to-one correspondence between geodesically equivalent metrics and nondegenerate symmetric (0,2) tensors a_{ij} satisfying the equations

$$a_{ij,k} = \frac{1}{2}(a_{\alpha,i}^{\alpha}g_{jk} + a_{\alpha,j}^{\alpha}g_{ik}), \quad (1)$$

where $a_{\alpha}^{\alpha} = a_{\alpha\beta}g^{\alpha\beta}$, and the g^{ij} are the elements of the inverse matrix to g_{ij} , and the commas denote covariant differentiation with respect to the connection on (M, g) . These equations are linear, so that their solutions form a linear vector space; the dimension of this space is called the *degree of geodesic mobility* of the metric g and denoted by p . The number p is a numerical characteristic of the cardinality of the geodesic class of the given metric g_{ij} (see [1]).

It has long been known that metrics with large degree of mobility admit concircular covector fields [2]. Recall that a covector field φ_i on (M, g) is said to be *concircular* if

$$\varphi_{i,j} = \rho g_{ij} \quad (2)$$

for some function ρ on the manifold (M, g) .

We denote the linear space of concircular vector fields in the metric g_{ij} by $\text{Con}(M)$.

The following assertion was stated in [3].

Theorem 1. *The degree of geodesic mobility of a Riemannian (with positive definite metric) space (M, g) of dimension $n \geq 3$ of nonconstant curvature can take only the values $p = m(m+1)/2 + l$, where $m = \dim \text{Con}(M)$, and l ranges from 1 to $L = [(n+1-m)/3]$, where the brackets denote the integer part of a number.*

Unfortunately, this assertion is incorrect. Indeed, in the dimension $n = 4$, it follows from this theorem that the degree of mobility is 2 if and only if the number of linearly independent concircular vector fields is 1. In other words, according to the theorem, there exist no 4-spaces with degree of mobility $p \geq 2$ that admit no concircular vector fields. However, such metric spaces exist. An example of a metric with the required property is the restriction of the standard metric $dx_1^2 + dx_2^2 + \dots + dx_5^2$ on Euclidean space \mathbb{R}^5 to the standard ellipsoid

$$\left\{ (x_1, x_2, \dots, x_5) \in \mathbb{R}^5 \mid \frac{x_1^2}{a_1} + \frac{x_2^2}{a_2} + \dots + \frac{x_5^2}{a_5} = 1 \right\}, \quad \text{where } 0 < a_1 < a_2 < \dots < a_5.$$

It was shown in [4]–[6] that the metric on the ellipsoid admits a nontrivial geodesic equivalence. Therefore, the degree of mobility of this metric is at least 2. On the other hand, the metric on the

*E-mail: vladimir.matveev@uni-jena.de

ellipsoid admits no concircular vector fields. To show this, consider conditions (2), which are a system of differential equations for the components of the vector φ_i . Covariant differentiation and alternation with Ricci's identity taken into account yield the integrability conditions

$$\varphi_\alpha R_{ijk}^\alpha = \rho_k g_{ij} - \rho_j g_{ik} \quad (3)$$

for this system. Here R_{jkl}^i is the Riemann tensor and $\rho_i := \rho_{,i}$. Contracting Eq. (3), we obtain

$$\varphi^\alpha R_{\alpha i} = (n-1)\rho_i,$$

where R_{ij} is the Ricci tensor, $\varphi^i = \varphi_\alpha g^{\alpha i}$, and the g^{ij} are the elements of the inverse matrix of the metric. This reduces (3) to the form

$$\varphi^\alpha W_{\alpha ij}^h = 0, \quad (4)$$

where W_{ijk}^h is the Weyl projective curvature tensor. A direct calculation shows that the Weyl tensor of the ellipsoid admits no nontrivial vector fields satisfying conditions (4).

Nevertheless, the main idea of [3] is correct; using this idea, we obtain the following theorem.

Theorem 2. *The degree of mobility of a Riemannian n -space ($n \geq 3$) of nonconstant curvature can take either the values $p = m(m+1)/2 + l$, where $m = \dim \text{Con}(M)$, and l ranges from 1 to $L = [(n+1-m)/3]$, where the square brackets denote the integer part of a number, or $p = 1, 2$.*

The difference between Theorem 2 and Theorem 1 is that in Theorem 2, the degree of mobility can take the values 1 and 2, among others; the case $p \leq 2$ is a special case not related to the number of concircular vector fields.

The mistake in the proof of Theorem 1 is related to this special case $p \leq 2$. The proof of Theorem 1 assumes implicitly that the space under consideration is $V_n(B)$ [7], [8]. However, not every space admitting $p = 2$ is the space $V_n(B)$. The metric on the ellipsoid mentioned above is not a $V_n(B)$ metric, because every $V_n(B)$ -metric on a closed manifold must be of constant curvature [9], [10], [11].

On the other hand, as shown in [7], [8], for $p \geq 3$, any metric is a $V_n(B)$ metric.

Thus, the proof given in [3] is correct under the additional assumption $p > 2$, and the words "or $p = 1, 2$ " render the theorem valid.

ACKNOWLEDGMENTS

V. A. Kiosak and V. S. Matveev acknowledge the support of German Scientific Society (the Deutsche Forschungsgemeinschaft grant SPP 1154—Globale Differentialgeometrie). J. Mikeš acknowledges the support of Czech Grant Agency (The Council of Czech Government grants MSM 6198959214 and MEB 040907).

REFERENCES

1. N. S. Sinyukov, *Geodesic Mappings of Riemannian Spaces* (Nauka, Moscow, 1979) [in Russian].
2. J. Mikeš, in *Modern Mathematics: Subject Surveys*, Vol. 11: *Geometry—2*, Itogi Nauki i Tekhniki (VINITI, Moscow, 2002), pp. 121–162 [J. Math. Sci. **78** (3), 311 (1996)].
3. I. G. Shandra, *Mat. Zametki* **68** (4), 620 (2000) [Math. Notes **68** (3–4), 528 (2000)].
4. V. S. Matveev and P. Ī. Topalov, *Regul. Chaotic Dyn.* **3** (2), 30 (1998).
5. S. Tabachnikov, *Comment. Math. Helv.* **74** (2), 306 (1999).
6. P. Topalov, *Acta Appl. Math.* **59** (3), 271 (1999).
7. A. S. Solodovnikov, *Trudy Sem. Vektor. Tenzor. Anal.* **11**, 43 (1961).
8. V. A. Kiosak and J. Mikeš, in *The Geometry of Embedded Manifolds* (Moskov. Gos. Ped. Inst., Moscow, 1986), pp. 35–39 [in Russian].
9. V. S. Matveev, in *Adv. Stud. Pure Math.*, Vol. 43: *Singularity Theory and its Applications* (Math. Soc. Japan, Tokyo, 2006), pp. 221–250.
10. V. S. Matveev, *J. Differential Geom.* **75** (3), 459 (2007).
11. V. S. Matveev, *Projective Lichnerowicz–Obata Conjecture*, arXiv: math. DG/0407337.