

# NON-SMOOTH SADDLE-NODE BIFURCATIONS II: DIMENSIONS OF STRANGE ATTRACTORS

G. Fuhrmann <sup>\*</sup>      M. Gröger <sup>†</sup>      T. Jäger <sup>‡</sup>

19th December 2014

We study the geometric and topological properties of strange non-chaotic attractors created in non-smooth saddle-node bifurcations of quasiperiodically forced interval maps. By interpreting the attractors as limit objects of the iterates of a continuous curve and controlling the geometry of the latter, we determine their Hausdorff and box-counting dimension and show that these take distinct values. Moreover, the same approach allows to describe the topological structure of the attractors and to prove their minimality.

## 1 Introduction

One of the most intriguing phenomena in dynamical systems is the existence of strange attractors and the fact that these intricate structures already occur for relatively simple deterministic systems given by low-dimensional maps and flows. The discovery of paradigm examples like the Hénon or the Lorenz attractor has given great impetus to the field. Usually, strange attractors are associated with chaotic dynamics. However, this is not always the case, and in a seminal paper [1] Grebogi, Ott, Pelikan and Yorke demonstrated that such objects may also occur in systems which do not allow for chaotic motion – in the sense of positive topological entropy – for structural reasons. Their heuristic and numerical arguments were later confirmed in a rigorous analysis by Keller [2]. The class of systems considered in [1, 2] were *quasiperiodically forced (qpf) monotone interval maps*. These are skew product transformations of the form

$$f: \mathbb{T}^d \times X \rightarrow \mathbb{T}^d \times X, \quad (\theta, x) \mapsto (\theta + \omega, f_\theta(x)), \quad (1.1)$$

where  $\mathbb{T}^d = \mathbb{R}^d / \mathbb{Z}^d$ ,  $X \subseteq \mathbb{R}$  is an interval (possibly non-compact), the rotation vector  $\omega \in \mathbb{T}^d$  on the base is totally irrational and for each  $\theta \in \mathbb{T}^d$  the *fibre map*  $f_\theta: X \rightarrow X$  is a monotone interval map.<sup>1</sup>

<sup>\*</sup>Department of Mathematics, TU Dresden, Germany. Email: Gabriel.Fuhrmann@mailbox.tu-dresden.de

<sup>†</sup>Department of Mathematics, Universität Bremen, Germany. Email: groeger@math.uni-bremen.de

<sup>‡</sup>Department of Mathematics, TU Dresden, Germany. Email: Tobias.Oertel-Jaeger@tu-dresden.de

<sup>1</sup>The fact that skew product systems of this type do not allow for positive entropy follows from an old result of Bowen [3], see also [4].

---

The specific examples in [1, 2] belong to the class of so-called *pinched skew products*, which are characterised by the fact that for some  $\theta \in \mathbb{T}^d$  the fibre map  $f_\theta$  is constant and consequently the whole fibre  $\{\theta\} \times X$  is mapped to a single point [5]. This greatly simplifies their analysis, but at the same time it gives them a certain toy model character. In particular, pinched skew products are not invertible and can therefore not be the time-one maps of flows, which are of main interest from the applied point of view. Notwithstanding, it was later confirmed both numerically (e.g. [6, 7]) and even experimentally [8, 9] that the occurrence of strange non-chaotic attractors (SNA's) in systems with quasiperiodic forcing is a widespread and robust phenomenon, and general methods to rigorously prove their existence have been established in different settings [10, 11, 12, 13, 14]. Thereby, it has turned out that SNA's often play a crucial role in the bifurcations of invariant curves and often originate from the collision of these. This pattern for the creation of SNA's has been named *torus collision* or, more specifically, *non-smooth saddle-node bifurcation* [15, 16, 17].

In contrast to conditions for the existence of SNA's, the structural properties of these objects are far less understood. From the mathematical viewpoint, much of the relevant information about the geometric and dynamical features of an attractor is encoded in different notions of dimension. Accordingly, the question of computing dimensions of SNA's has been raised already at an early stage. Based on numerical evidence, it has been conjectured in [18] that the box (or capacity) dimension of SNA's appearing in different types of qpf systems with one-dimensional base  $\mathbb{T}^1$  and one-dimensional fibres equals two, whereas the information dimension equals one. For the simple pinched skew products introduced in [1], these findings were confirmed analytically in [19, 20].

The aim here is to perform a similar analysis for SNA's appearing in a more realistic setting. We concentrate on invertible qpf interval maps and focus on such SNA's which are created in non-smooth saddle-node bifurcations. Apart from the dimensions, we obtain the minimality of the dynamics on the attractors and information about their topological structure. On an heuristic level, some inspiration is drawn from the previous work in [19, 20]. Technically, however, the task is considerably more demanding and our approach builds on a detailed multiscale analysis established in the first author's article [14], whose continuation this work presents. Before stating precise results, we need to introduce some general notions and a framework for non-smooth saddle-node bifurcations in qpf interval maps. The latter results from a discrete-time analogue to work of Núñez and Obaya on almost periodically forced scalar differential equations [21], which is provided in [17].

Given  $f$  as in (1.1), an *f-invariant graph* is a measurable function  $\phi : \mathbb{T}^d \rightarrow X$  that satisfies

$$f_\theta(\phi(\theta)) = \phi(\theta + \omega)$$

for all  $\theta \in \mathbb{T}^d$ . The associated point set  $\Phi = \{(\theta, \phi(\theta)) \mid \theta \in \mathbb{T}^d\}$  is invariant in this case, and slightly abusing terminology we will refer to both the function  $\phi$  and the set  $\Phi$  as an invariant graph. As far as functions are concerned, we will not distinguish between invariant graphs that coincide Lebesgue-almost everywhere, and thus implicitly speak of equivalence classes. By saying an invariant graph has a certain property, like continuity or semi-continuity, we mean that there exists a representative in the respective equivalence class which has this property. The stability of an invariant graph is determined by its Lyapunov exponent

$$\lambda(\phi) = \int_{\mathbb{T}^d} \log f'_\theta(\phi(\theta)) d\theta.$$

If  $\lambda(\phi) < 0$ , then  $\phi$  is attracting, in the sense that for almost every  $\theta \in \mathbb{T}^d$  there is  $\varepsilon = \varepsilon(\theta) > 0$  such that

$$|f^n(\theta, x) - (\theta + n\omega, \phi(\theta + n\omega))| \rightarrow 0$$

for  $n \rightarrow \infty$  and  $x \in B_\varepsilon(\phi(\theta))$  [22]. If  $\phi$  is continuous, then  $\varepsilon$  can be chosen independent of  $\theta \in \mathbb{T}^d$  [23]. An SNA, in this setting, is a non-continuous invariant graph with a negative Lyapunov exponent. ‘Strange’ here simply refers to the lack of continuity. We refer to Milnor [24] for a broader discussion of the notion of ‘strange attractors’.

In the context of forced systems, the significance of invariant graphs stems from the fact that they are a natural analogue to fixed points of unperturbed maps, and just like the latter they may bifurcate. As mentioned above, we will concentrate on saddle-node bifurcations. In order to keep notation as simple as possible, we may assume without loss of generality that  $[0, 1] \subseteq X$  from now on. We denote by  $\mathcal{F}_\omega$  the class of  $C^2$ -maps of the form (1.1) (with fixed rotation vector  $\omega \in \mathbb{T}^d$  in the base). Further, by  $\mathcal{P}_\omega$  we denote  $C^2$  one-parameter families in  $\mathcal{F}_\omega$ , that is,

$$\mathcal{P}_\omega = \left\{ (f_\beta)_{\beta \in [0,1]} \mid f_\beta \in \mathcal{F}_\omega \text{ for all } \beta \in [0, 1] \text{ and } (\beta, \theta, x) \mapsto f_{\beta,\theta}(x) \text{ is } C^2 \right\}.$$

Elements of  $\mathcal{P}_\omega$  will also be denoted by  $\hat{f} = (f_\beta)_{\beta \in [0,1]}$ . We equip  $\mathcal{P}_\omega$  with the  $C^2$ -metric and simply refer to the induced topology as  $C^2$ -topology in all of the following. In order to ensure the occurrence of a saddle-node bifurcation in a prescribed region  $\Gamma = \mathbb{T}^d \times [0, 1]$  of the phase space, we need to impose a number of further conditions. The following assumptions are supposed to hold for all  $\beta \in [0, 1]$  and all  $\theta \in \mathbb{T}^d$  (if applicable).

$$f_{\beta,\theta}(0) \leq 0 \quad \text{and} \quad f_{\beta,\theta}(1) \leq 1; \quad (1.2)$$

$$f'_{\beta,\theta}(x) > 0 \quad \text{for all } x \in [0, 1]; \quad (1.3)$$

$$f''_{\beta,\theta}(x) < 0 \quad \text{for all } x \in [0, 1]; \quad (1.4)$$

$$\frac{\partial}{\partial \beta} f'_{\beta,\theta}(x) < 0 \quad \text{for all } x \in [0, 1]; \quad (1.5)$$

$$f_0 \text{ has two continuous invariant graphs in } \Gamma \text{ and } f_1 \text{ has no invariant graph in } \Gamma. \quad (1.6)$$

Here, we say  $f$  has an invariant graph  $\phi$  in  $\mathbb{T}^d \times A$  if  $\phi(\theta) \in A$  for all  $\theta \in \mathbb{T}^d$ . We let

$$\mathcal{S}_\omega = \left\{ \hat{f} \in \mathcal{P}_\omega \mid \hat{f} \text{ satisfies (1.2)–(1.6)} \right\}.$$

**Theorem 1.1** ([17, Theorem 6.1]). *Let  $\hat{f} = (f_\beta)_{\beta \in [0,1]} \in \mathcal{S}_\omega$ . Then there exists a unique critical parameter  $\beta_c \in (0, 1)$  such that the following holds.*

- (i) *If  $\beta < \beta_c$ , then  $f_\beta$  has two invariant graphs  $\phi_\beta^- < \phi_\beta^+$  in  $\Gamma$ , both of which are continuous. We have  $\lambda(\phi_\beta^-) > 0$  and  $\lambda(\phi_\beta^+) < 0$ .*
- (ii) *If  $\beta > \beta_c$ , then  $f_\beta$  has no invariant graphs in  $\Gamma$ .*
- (iii) *If  $\beta = \beta_c$ , then one of the following two possibilities hold.*

- 
- (S) Smooth bifurcation:  $f_{\beta_c}$  has a unique invariant graph  $\phi_{\beta_c}$  in  $\Gamma$ , which satisfies  $\lambda(\phi_{\beta_c}) = 0$ . Either  $\phi$  is continuous, or it contains both an upper and lower semi-continuous representative in its equivalence class.
- (N) Non-smooth bifurcation:  $f_{\beta_c}$  has exactly two invariant graphs  $\phi_{\beta_c}^- < \phi_{\beta_c}^+$  a.e. in  $\Gamma$ . The graph  $\phi_{\beta_c}^-$  is lower semi-continuous, whereas  $\phi_{\beta_c}^+$  is upper semi-continuous, but none of the graphs is continuous and there exists a residual set  $\Omega \subseteq \mathbb{T}^d$  such that  $\phi_{\beta_c}^-(\theta) = \phi_{\beta_c}^+(\theta)$  for all  $\theta \in \Omega$ .

*Remark.* The points in the above set  $\Omega$  are called *pinched points*. Due to the semi-continuity, it turns out that  $\phi_{\beta_c}^+$  and  $\phi_{\beta_c}^-$  are actually continuous in the pinched points (cf. [25, Lemma 5]).

As said before, the invariant graphs appearing in this statement have to be understood in the sense of equivalence classes. There is, however, an intimate relation to the maximal invariant subset of  $\Gamma$ , given by

$$\Lambda_\beta = \bigcap_{n \in \mathbb{Z}} f_\beta^n(\Gamma),$$

that can be used to obtain well-defined canonical representatives. This will be important in the statement of our main result. We write

$$\Lambda_{\beta, \theta} = \{x \in [0, 1] \mid (\theta, x) \in \Lambda_\beta\}.$$

Due to the invariance of  $\Lambda_\beta$  and the monotonicity of the fibre map (1.3), the graphs

$$\hat{\phi}_\beta^-(\theta) = \inf \Lambda_{\beta, \theta} \quad \text{and} \quad \hat{\phi}_\beta^+(\theta) = \sup \Lambda_{\beta, \theta} \quad (1.7)$$

are both invariant and thus have to be representatives of the invariant graphs in part (i) and (iii) of Theorem 1.1. Moreover, if we write  $[\hat{\phi}_\beta^-, \hat{\phi}_\beta^+] = \{(\theta, x) \in \Gamma \mid \hat{\phi}_\beta^-(\theta) \leq x \leq \hat{\phi}_\beta^+(\theta)\}$ , then  $\Lambda_\beta = [\hat{\phi}_\beta^-, \hat{\phi}_\beta^+]$ .

Theorem 1.1 gives a precise meaning to the notion of a saddle-node bifurcation for a family in  $\mathcal{S}_\omega$ . Moreover, it shows that there are two qualitatively different patterns for such a transition, namely the smooth and the non-smooth case. While smooth bifurcations can be realised easily by considering direct products of irrational rotations and suitable interval maps, the existence of non-smooth bifurcations is much more difficult to establish. However, as the following result shows, they are nevertheless a generic case. Recall that  $\omega \in \mathbb{T}^d$  is *Diophantine* if there exist  $\mathcal{C} > 0$  and  $\eta > 1$  such that  $d(k\omega, 0) \geq \mathcal{C}|k|^{-\eta}$  for all  $k \in \mathbb{Z} \setminus \{0\}$ .

**Theorem 1.2** ([14]). *Let*

$$\mathcal{N}_\omega = \{\hat{f} \in \mathcal{S}_\omega \mid f_{\beta_c} \text{ satisfies (N)}\}$$

*and suppose  $\omega \in \mathbb{T}^d$  is Diophantine. Then  $\mathcal{N}_\omega$  has non-empty interior in the  $C^2$ -topology on  $\mathcal{P}_\omega$ .*

While this statement may seem rather abstract in the above form, it is important to note that a much more detailed version is given in [14]. It states that  $\mathcal{N}_\omega$  contains a  $C^2$ -open subset  $\mathcal{U}_\omega$  which is completely characterised by a list of  $C^2$ -estimates on the respective parameter families. However, since this list consists of 16 different and sometimes rather technical conditions, we refrain from reproducing it here. A partially intrinsic characterisation that contains all the information required for our purposes is given in Section 2.3. In order to fix ideas, readers may restrict their attention to the following explicit example which satisfies all the assumptions of our main result below.

---

**Proposition 1.3** ([14]). *Let  $\omega \in \mathbb{T}^d$  be Diophantine. Then there exists  $a_0 > 0$  such that for all  $a > a_0$  the parameter family  $\hat{f} \in \mathcal{S}_\omega$  given by*

$$f_\beta(\theta, x) = \left( \theta + \omega, \frac{2}{\pi} \arctan(ax) - \beta(1 + \cos(2\pi\theta)) \right) \quad (1.8)$$

*undergoes a non-smooth saddle-node bifurcation, that is,  $\hat{f} \in \mathcal{N}_\omega$ .*

Our main result now provides information on the geometric and topological structure of the SNA and the associated ergodic measure occurring in such non-smooth saddle-node bifurcations. Note that to each invariant graph  $\phi$  an invariant ergodic measure  $\mu_\phi$  can be associated by defining

$$\mu_\phi(A) = \text{Leb}_{\mathbb{T}^d}(\pi_{\mathbb{T}^d}(\Phi \cap A)),$$

where  $A \subseteq \mathbb{T}^d \times X$  is Borel measurable and  $\pi_{\mathbb{T}^d}$  is the canonical projection onto  $\mathbb{T}^d$ . We denote the box-counting dimension of a set  $A \subseteq \mathbb{T}^d \times X$  by  $D_B(A)$  and its Hausdorff dimension by  $D_H(A)$ . For the explanation of further dimension-theoretical notions, see Sections 2.1 and 2.2.

**Theorem 1.4.** *Let  $\omega \in \mathbb{T}^d$  be Diophantine. Then there exists a set  $\widehat{\mathcal{U}}_\omega \subseteq \mathcal{N}_\omega$  with non-empty  $\mathcal{C}^2$ -interior such that for all  $\hat{f} \in \widehat{\mathcal{U}}_\omega$  the SNA  $\hat{\phi}_{\beta_c}^+$  appearing at the critical bifurcation parameter satisfies the following.*

- (i)  $D_B(\hat{\Phi}_{\beta_c}^+) = d + 1$  and  $D_H(\hat{\Phi}_{\beta_c}^+) = d$ .
- (ii) The measure  $\mu_{\hat{\phi}_{\beta_c}^+}$  is exact dimensional with pointwise dimension and information dimension equal to  $d$ .
- (iii) The set  $\Lambda_{\beta_c} = [\hat{\phi}_{\beta_c}^-, \hat{\phi}_{\beta_c}^+]$  is minimal and we have  $\Lambda_{\beta_c} = \text{cl}(\hat{\Phi}_{\beta_c}^-) = \text{cl}(\hat{\Phi}_{\beta_c}^+)$ .
- (iv) The graph  $\hat{\phi}_{\beta_c}^+$  is the only semi-continuous representative in the equivalence class  $\phi_{\beta_c}^+$ .

*Analogous results hold for the repeller  $\phi_{\beta_c}^-$ . Moreover, for all sufficiently large  $a > 0$ , the parameter family  $\hat{f}$  given by (1.8) is contained in  $\widehat{\mathcal{U}}_\omega$ .*

Property (iii) has already been considered by M. Herman [26]. We want to mention that it has been proved previously by Bjerklöv for invariant graphs appearing in quasiperiodic Schrödinger cocycles [27], which can be considered a special case of our setting. Our proof is inspired by that of Bjerklöv, but puts a stronger focus on the global approximation of the SNA by iterates of continuous curves. This allows to avoid some technical complications. The strategy of our proof is outlined at the beginning of Section 3.

We also note that the result on the box-counting dimension is a direct consequence of (iii). Since the box-counting dimension is stable under taking closures, we have  $D_B(\hat{\phi}_{\beta_c}^+) = D_B(\Lambda_{\beta_c})$ . Since the bounding graphs of  $\Lambda_{\beta_c}$  are distinct, this set has positive  $d + 1$ -dimensional Lebesgue measure and therefore box-counting dimension  $d + 1$ .

---

**Acknowledgements.** This work was supported by an Emmy-Noether-Grant of the German Research Council (DFG grant JA 1721/2-1) and is part of the activities of the Scientific Network “Skew product dynamics and multifractal analysis” (DFG grant OE 538/3-1).

## 2 Preliminaries

### 2.1 Hausdorff and box-counting dimension

In the following, we recall the definition of the Hausdorff and box-counting dimension. Further, we state some well known properties that will be used later on. Suppose  $Y$  is a metric space. We denote the diameter of a subset  $A \subseteq Y$  by  $|A|$ . For  $\varepsilon > 0$ , we call a finite or countable collection  $\{A_i\}$  of subsets of  $Y$  an  $\varepsilon$ -cover of  $A$  if  $|A_i| \leq \varepsilon$  for each  $i$  and  $A \subseteq \bigcup_i A_i$ .

**Definition 2.1.** For  $A \subseteq Y$ ,  $s \geq 0$  and  $\varepsilon > 0$ , we define

$$\mathcal{H}_\varepsilon^s(A) := \inf \left\{ \sum_i |A_i|^s \mid \{A_i\} \text{ is an } \varepsilon\text{-cover of } A \right\}$$

and call

$$\mathcal{H}^s(A) := \lim_{\varepsilon \rightarrow 0} \mathcal{H}_\varepsilon^s(A)$$

the  $s$ -dimensional Hausdorff measure of  $A$ . The Hausdorff dimension of  $A$  is defined by

$$D_H(A) := \sup\{s \geq 0 \mid \mathcal{H}^s(A) = \infty\}.$$

The proof of the next lemma is straightforward (cf. [20], for example).

**Lemma 2.2.** Let  $A \subseteq Y$  be a lim sup set, meaning that there exists a sequence  $(A_i)_{i \in \mathbb{N}}$  of subsets of  $Y$  with

$$A = \limsup_{i \rightarrow \infty} A_i := \bigcap_{i=1}^{\infty} \bigcup_{k=i}^{\infty} A_k.$$

If  $\sum_{i=1}^{\infty} |A_i|^s < \infty$  for some  $s > 0$ , then  $\mathcal{H}^s(A) = 0$  and  $D_H(A) \leq s$ .

**Lemma 2.3** ([28]). Let  $Y$  and  $Z$  be two metric spaces and assume that  $g : A \subseteq Y \rightarrow Z$  is a bi-Lipschitz continuous map. Then  $D_H(g(A)) = D_H(A)$ .

**Lemma 2.4** ([28]). The Hausdorff dimension is countably stable, i.e.,  $D_H(\bigcup_i A_i) = \sup_i D_H(A_i)$  for any sequence of subsets  $(A_i)_{i \in \mathbb{N}}$  with  $A_i \subseteq Y$ .

**Definition 2.5.** The lower and upper box-counting dimension of a totally bounded subset  $A \subseteq Y$  are defined as

$$\underline{D}_B(A) := \liminf_{\varepsilon \rightarrow 0} \frac{\log N(A, \varepsilon)}{-\log \varepsilon},$$

$$\overline{D}_B(A) := \limsup_{\varepsilon \rightarrow 0} \frac{\log N(A, \varepsilon)}{-\log \varepsilon},$$

---

where  $N(A, \varepsilon)$  is the smallest number of sets of diameter at most  $\varepsilon$  needed to cover  $A$ . If  $\underline{D}_B(A) = \overline{D}_B(A)$ , then we call their common value  $D_B(A)$  the *box-counting dimension* (or *capacity*) of  $A$ .

*Remark.* In contrast to the last lemma, we only have that the upper box-counting dimension is finitely stable. Further,  $D_B(A) = D_B(\overline{A})$ .

**Theorem 2.6** ([29]). *Suppose  $Y$  and  $Z$  are two metric spaces and consider the Cartesian product space  $Y \times Z$  equipped with the maximum metric. Then for  $A \subseteq Y$  and  $B \subseteq Z$  totally bounded, we have*

$$D_H(A \times B) \leq D_H(A) + \overline{D}_B(B).$$

## 2.2 Exact dimensional and rectifiable measures

We recall the notions of pointwise and information dimension as well as exact dimensional measures. Further, we provide the definition and some properties of rectifiable measures where we mainly follow [30].

Again, let  $Y$  be a metric space. For  $x \in Y$ ,  $\varepsilon > 0$  let  $B_\varepsilon(x)$  be the open ball around  $x$  with radius  $\varepsilon > 0$ .

**Definition 2.7.** Suppose  $\mu$  is a finite Borel measure in  $Y$ . For each point  $x$  in the support of  $\mu$  we define the *lower* and *upper pointwise dimension* of  $\mu$  at  $x$  as

$$\underline{d}_\mu(x) := \liminf_{\varepsilon \rightarrow 0} \frac{\log \mu(B_\varepsilon(x))}{\log \varepsilon},$$

$$\overline{d}_\mu(x) := \limsup_{\varepsilon \rightarrow 0} \frac{\log \mu(B_\varepsilon(x))}{\log \varepsilon}.$$

If  $\underline{d}_\mu(x) = \overline{d}_\mu(x)$ , then their common value  $d_\mu(x)$  is called the *pointwise dimension* of  $\mu$  at  $x$ . The *information dimension* of  $\mu$  is defined as

$$\lim_{\varepsilon \rightarrow 0} \frac{\int \log \mu(B_\varepsilon(x)) d\mu(x)}{\log \varepsilon},$$

provided the limit exists. Otherwise, one again defines upper and lower information dimension via the limit superior and inferior, respectively.

**Definition 2.8.** We say that the measure  $\mu$  is *exact dimensional* if the pointwise dimension exists and is constant almost everywhere, i.e., we have

$$\underline{d}_\mu(x) = \overline{d}_\mu(x) =: d_\mu$$

$\mu$ -almost everywhere.

*Remark.* Note that if  $\mu$  is exact dimensional, then in the setting of separable metric spaces several other dimensions of  $\mu$  coincide with the pointwise dimension [31]. In particular, this is true for the information dimension [32, 33].

---

**Definition 2.9.** For  $d \in \mathbb{N}$ , we call a Borel set  $A \subseteq Y$  *countably  $d$ -rectifiable* if there exists a sequence of Lipschitz continuous functions  $(g_i)_{i \in \mathbb{N}}$  with  $g_i : A_i \subseteq \mathbb{R}^d \rightarrow Y$  such that  $\mathcal{H}^d(A \setminus \bigcup_i g_i(A_i)) = 0$ . A finite Borel measure  $\mu$  is called  *$d$ -rectifiable* if  $\mu = \Theta \mathcal{H}^d|_A$  for some countably  $d$ -rectifiable set  $A$  and some Borel measurable density  $\Theta : A \rightarrow [0, \infty)$ .

Observe that, by the Radon-Nikodym theorem,  $\mu$  is  $d$ -rectifiable if and only if  $\mu$  is absolutely continuous with respect to  $\mathcal{H}^d|_A$  where  $A$  is a countably  $d$ -rectifiable set.

**Theorem 2.10** ([30, Theorem 5.4]). *For a  $d$ -rectifiable measure  $\mu = \Theta \mathcal{H}^d|_A$ , we have*

$$\Theta(x) = \lim_{\varepsilon \rightarrow 0} \frac{\mu(B_\varepsilon(x))}{V_d \varepsilon^d},$$

for  $\mathcal{H}^d$ -a.e.  $x \in A$ , where  $V_d$  is the volume of the  $d$ -dimensional unit ball. The right-hand side of this equation is called the  $d$ -density of  $\mu$ .

From the last theorem, we can deduce that the  $d$ -density exists and is positive  $\mu$ -almost everywhere for a  $d$ -rectifiable measure  $\mu$ . This directly implies the next corollary.

**Corollary 2.11.** *A  $d$ -rectifiable measure  $\mu$  is exact dimensional with  $d_\mu = d$ .*

### 2.3 Definition of the set $\widehat{\mathcal{U}}_\omega$

The aim of this section is to define the set  $\widehat{\mathcal{U}}_\omega$  in Theorem 1.4. In principle, it would be possible to work directly with the set  $\mathcal{U}_\omega$  mentioned after Theorem 1.1, which can be defined in terms of the explicit  $C^2$ -estimates used in [14]. However, as mentioned we want to avoid reproducing the somewhat technical characterisation. At the same time, we have to state a number of facts concerning the dynamics of the considered parameter families at the bifurcation, which are derived by means of the multiscale analysis carried out in [14].

Hence, what we actually do is to omit all those estimates from [14] which are only needed to prove the desired dynamical properties—namely certain slow recurrence conditions for certain critical sets defined in the multiscale analysis. Instead, we define  $\widehat{\mathcal{U}}_\omega$  as the set of parameter families which satisfy those  $C^2$ -estimates that are still needed for our purposes and at the same time show the required dynamical behaviour. This means that  $\widehat{\mathcal{U}}_\omega$  will be defined in a partially intrinsic and somewhat abstract way. However, the important fact is that it has non-empty  $C^2$ -interior (see Proposition 2.15) and contains the example (1.8) for large  $a$ .

In the following, let  $f \in \mathcal{F}_\omega$  be given. We assume the existence of both an *interval of contraction*  $C = [c, 1] \subseteq X$  and *expansion*  $E = [0, e] \subseteq X$  where  $0 < e < c < 1$  (the naming becomes clear below) and a closed convex region  $\mathcal{I}_0 \subseteq \mathbb{T}^d$ , called the (*first*) *critical region*, such that

$$f_\theta(x) \in C \text{ for all } x \in [e, 1] \text{ and } \theta \notin \mathcal{I}_0. \quad (2.1)$$



Further, we suppose there are  $\alpha > 1$ ,  $p \geq \sqrt{2}$  and  $S > 0$  such that for arbitrary  $\theta, \theta' \in \mathbb{T}^d$  we have

$$\alpha^{-p}|x - x'| \leq |f_\theta(x) - f_\theta(x')| \leq \alpha^p|x - x'| \text{ for all } x, x' \in X, \quad (2.2)$$

$$|f_\theta(x) - f_{\theta'}(x)| \leq Sd(\theta, \theta') \text{ for all } x \in X, \quad (2.3)$$

$$|f_\theta(x) - f_\theta(x')| \leq \alpha^{-2/p}|x - x'| \text{ for all } x, x' \in C, \quad (2.4)$$

$$|f_\theta(x) - f_\theta(x')| \geq \alpha^{2/p}|x - x'| \text{ for all } x, x' \in E. \quad (2.5)$$

These are the explicit estimates needed to define  $\widehat{\mathcal{U}}_\omega$ . In order to state the required dynamical properties, let  $K_n = K_0\kappa^n$  for some integers  $\kappa \geq 2$ ,  $K_0 \in \mathbb{N}$ . Set

$$b_0 := 1, \quad b_n := (1 - 1/K_{n-1})b_{n-1} \quad (n \in \mathbb{N})$$

and  $b := \lim_{n \rightarrow \infty} b_n$  and assume  $K_0$  and  $\kappa$  are big enough to ensure that  $b > \sqrt{(p^2 + 1)/(p^2 + 2)}$ . Further, let  $(M_n)_{n \in \mathbb{N}_0}$  be a sequence of integers that satisfies  $M_n \in [K_{n-1}M_{n-1}, 2K_{n-1}M_{n-1} - 2]$  for all  $n \in \mathbb{N}$ , where  $M_0 \geq 2$ .

**Definition 2.12.** For  $n \in \mathbb{N}_0$ , we recursively define the  $n + 1$ -th *critical region*  $\mathcal{I}_{n+1}$  in the following way:

- $\mathcal{A}_n := (\mathcal{I}_n - (M_n - 1)\omega) \times C$ ,
- $\mathcal{B}_n := (\mathcal{I}_n + (M_n + 1)\omega) \times E$ ,
- $\mathcal{I}_{n+1} := \pi_{\mathbb{T}^d} \left( f^{M_n-1}(\mathcal{A}_n) \cap f^{-(M_n+1)}(\mathcal{B}_n) \right)$ .

Note that we trivially have  $\mathcal{I}_{n+1} \subseteq \mathcal{I}_n$ . For  $n \in \mathbb{N}_0$ , set  $\mathcal{Z}_n^- := \bigcup_{j=0}^n \bigcup_{l=-(M_j-2)}^0 \mathcal{I}_j + l\omega$ ;  $\mathcal{Z}_n^+ := \bigcup_{j=0}^n \bigcup_{l=1}^{M_j} \mathcal{I}_j + l\omega$ ;  $\mathcal{V}_n := \bigcup_{j=0}^n \bigcup_{l=1}^{M_j+1} \mathcal{I}_j + l\omega$ ;  $\mathcal{W}_n := \bigcup_{j=0}^n \bigcup_{l=-(M_j-1)}^0 \mathcal{I}_j + l\omega$ . Moreover, set  $\mathcal{V}_{-1}, \mathcal{W}_{-1} = \emptyset$ .

**Definition 2.13.** Let  $n \in \mathbb{N}_0$ . For  $c_0 > 0$ , set  $\varepsilon_n := c_0\alpha^{-M_{n-1} \cdot b/(2p)}$ , where we put  $M_{-1} = 0$  for convenience. We say  $f$  verifies  $(\mathcal{F}1)_n$  and  $(\mathcal{F}2)_n$ , respectively if  $\mathcal{I}_j \neq \emptyset$  and

$$(\mathcal{F}1)_n \quad d\left(\mathcal{I}_j, \bigcup_{k=1}^{2K_j M_j} \mathcal{I}_j + k\omega\right) > \varepsilon_j,$$

$$(\mathcal{F}2)_n \quad \left(\mathcal{I}_j - (M_j - 1)\omega \cup \mathcal{I}_j + (M_j + 1)\omega\right) \cap \left(\mathcal{V}_{j-1} \cup \mathcal{W}_{j-1}\right) = \emptyset$$

for  $j = 0, \dots, n$  and  $n \in \mathbb{N}_0$ . If  $f$  satisfies both  $(\mathcal{F}1)_n$  and  $(\mathcal{F}2)_n$ , we say  $f$  satisfies  $(\mathcal{F})_n$ . Further, we say  $f$  satisfies  $(\mathcal{E})_n$  if

$$(\mathcal{E})_n \quad |\mathcal{I}_n| < \varepsilon_n,$$

where  $|\mathcal{I}_n|$  denotes the diameter of  $\mathcal{I}_n \subseteq \mathbb{T}^d$ .

In the following, we say  $f$  satisfies (2.1)–(2.5),  $(\mathcal{F})_n$  and  $(\mathcal{E})_n$  if it verifies the respective assumptions for some choice of the above constants. With these notions, we are now in the position to define the set  $\widehat{\mathcal{U}}_\omega$ .

---

**Definition 2.14.** For  $\omega \in \mathbb{T}^d$ , set

$$\widehat{\mathcal{U}}_\omega = \{ \hat{f} \in \mathcal{S}_\omega \mid f_{\beta_c} \text{ satisfies (2.1)–(2.5), } (\mathcal{F})_n \text{ and } (\mathcal{E})_n \text{ for all } n \in \mathbb{N} \}.$$

The following result is now contained implicitly in [14], see [14, Theorem 4.18] and its proof.

**Proposition 2.15** ([14]). *For Diophantine  $\omega \in \mathbb{T}^d$ , the set  $\widehat{\mathcal{U}}_\omega$  has non-empty  $C^2$ -interior and we have  $\widehat{\mathcal{U}}_\omega \subseteq \mathcal{N}_\omega$ . Moreover, for all sufficiently large  $a > 0$ , the parameter family  $\hat{f}$  given by (1.8) is contained in  $\widehat{\mathcal{U}}_\omega$ .*

Thus, in order to prove Theorem 1.4, our only task is to show that the properties of the parameter families in  $\widehat{\mathcal{U}}_\omega$  stated in this section imply the assertions on the dimensions and the topological structure of  $\phi_{\beta_c}^+$  and  $\phi_{\beta_c}^-$ .

### 3 Hausdorff, pointwise and information dimension

Our analysis of the structure of the SNA  $\hat{\Phi}_{\beta_c}^+$  appearing in parameter families  $\hat{f} \in \widehat{\mathcal{U}}_\omega$  hinges on the fact that the function  $\hat{\phi}_{\beta_c}^+$  can be approximated by the images of the curve  $\mathbb{T}^d \times \{1\}$  under successive iterates of the map  $f_{\beta_c}$ . Since from now on the critical parameter  $\beta_c$  and thus also the map  $f_{\beta_c}$  are fixed, we suppress the parameter from the notation. Hence, from now on  $f$  will always denote a map that belongs to

$$\mathcal{V} = \{ f \in \mathcal{F}_\omega \mid f \text{ satisfies (1.2)–(1.4), (2.1)–(2.5) as well as } (\mathcal{F})_n \text{ and } (\mathcal{E})_n \text{ for all } n \in \mathbb{N} \}.$$

As before, we let

$$\Lambda = \bigcap_{n \in \mathbb{Z}} f^n(\Gamma)$$

be the maximal  $f$ -invariant set inside  $\Gamma$  and denote by  $\phi^-$  and  $\phi^+$  its bounding graphs, that is,  $\phi^-(\theta) = \inf \Lambda_\theta$  and  $\phi^+(\theta) = \sup \Lambda_\theta$  (cf. (1.7)). Now given  $\theta \in \mathbb{T}^d$ , let

$$\phi_n^+(\theta) := f_{\theta-n\omega}^n(1) = f_{\theta-\omega} \circ \dots \circ f_{\theta-n\omega}(1) \quad \text{and} \quad \phi_n^-(\theta) := f_{\theta+n\omega}^{-n}(0) = f_{\theta+\omega}^{-1} \circ \dots \circ f_{\theta+n\omega}^{-1}(0),$$

with  $f_\theta^n(x) = \pi_x \circ f^n(\theta, x)$  for all integers<sup>2</sup>  $n \in \mathbb{Z}$  where  $\pi_x$  is the projection to the second coordinate. We call  $\phi_n^+$  the  $n$ -th iterated upper boundary line and  $\phi_n^-$  the  $n$ -th iterated lower boundary line. Assumption (1.2) and the monotonicity (1.3) yield that  $(\phi_n^+)_{n \in \mathbb{N}}$  and  $(\phi_n^-)_{n \in \mathbb{N}}$  are monotonously decreasing and increasing, respectively. Moreover, it is easy to see from (1.3) that  $[\phi_n^-, \phi_n^+] = \bigcap_{k=-n}^n f^k(\Gamma)$ . As a consequence, it is immediate that

$$\phi^+(\theta) = \lim_{n \rightarrow \infty} \phi_n^+(\theta) \quad \text{and} \quad \phi^-(\theta) = \lim_{n \rightarrow \infty} \phi_n^-(\theta).$$

Thus, in order to draw conclusions on the structure of the bounding graphs, it is natural to study the iterated boundary lines first. Figure 1 shows the first 6 iterated boundary lines for the critical parameter in the example family (1.8) with  $\omega$  the golden mean and parameters  $a = 40$  and  $\beta_c \approx$

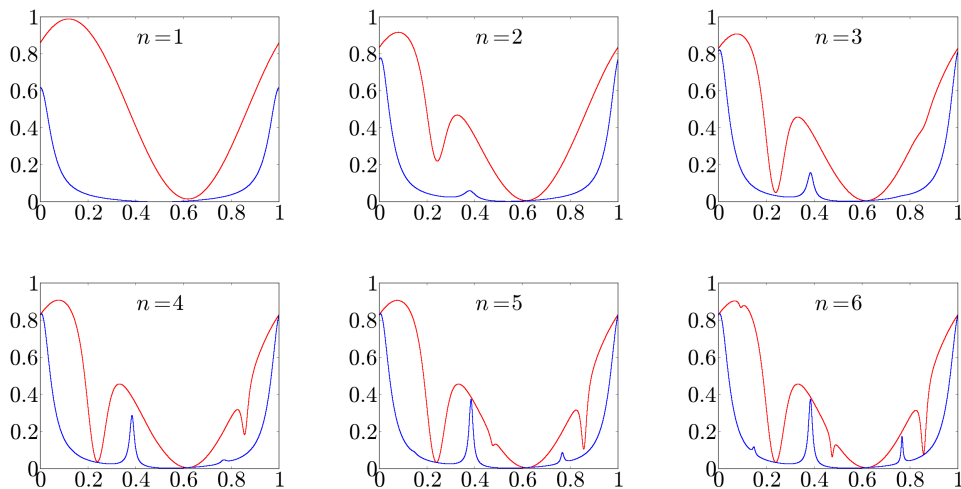


Figure 1: The first 6 iterated upper and lower boundary lines  $\phi_n^+$  (red) and  $\phi_n^-$  (blue), respectively, of the family (1.8) for  $a = 40$  at  $\beta = 0.48714$  with  $\omega$  the golden mean.

0.48714. These pictures reveal a very characteristic pattern. Let us look carefully at the evolution of  $\phi_n^+$ .

For  $n = 1$ , we see that a first peak exists in the vicinity of  $\theta = \omega$ , that is, above the set  $\mathcal{I}_0 + \omega$  (cf. (2.1)). After a second iteration, the image of this peak appears as a second peak in the vicinity of  $2\omega$  while outside this new peak the graph seems—more or less—unchanged. The second peak is not as pronounced as the first peak yet since the strong expansion close to the zero line (due to (2.5)) enlarged the tiny gap between  $\phi_1^+(\omega)$  and  $\phi_1^-(\omega)$ . However, after one more iteration, the second peak is *stabilised*, that is, its shape is essentially fixed for higher iterations. It is also important to observe that the graph outside this peak has not changed apart from a small neighbourhood of  $3\omega$  in the step from  $n = 2$  to  $n = 3$ . Furthermore, note that the second peak is of much smaller size than the first one.

Though the third peak around  $3\omega$  is already hardly visible at  $n = 3$ , it clearly stabilises until  $n = 6$  and the graph only changes close to  $4\omega$  and  $5\omega$  along this stabilisation. Altogether, this motivates the following qualitative claim.

*$\phi_{n+1}^+$  differs from  $\phi_n^+$  only in smaller and smaller neighbourhoods of those peaks around  $j\omega$  (for  $j = 1, \dots, n + 1$ ) which are not stabilised yet after  $n$  iterations.*

The point is that every peak eventually stabilises in those  $\theta$  which are not hit by peaks that appear at higher iterations. Moreover, the measure of these future peaks tends to zero. As  $\phi_j^+$  is Lipschitz-

<sup>2</sup> Note that the invariant graph  $\phi^- \geq 0$  cannot be crossed by any orbit. Hence, due to the monotonicity of  $f_\theta$  on all  $X$  (for each  $\theta$ ) as well as (1.2) and (1.3),  $f_\theta^{-n}(0)$  is indeed well-defined for all  $n \in \mathbb{N}$  and arbitrary  $\theta \in \mathbb{T}^d$ .

continuous with a Lipschitz constant  $L_j$ , the claim implies that we get essentially the same Lipschitz constant  $L_j$  for  $\phi_n^+$  (with arbitrary  $n \geq j$ ) at all those points at which  $\phi_j^+$  is stabilised already.

By this means, we are able to establish a decomposition of  $\phi^+$  into Lipschitz graphs whose Hausdorff dimension equals  $d$  (see Lemma 2.3). By the countable stability of the Hausdorff dimension (see Lemma 2.4), this yields that  $D_H(\Phi^+) = d$ . Part (iii) and (iv) of Theorem 1.4 are not so easy to illustrate on this qualitative level since we need some understanding of the local densities of those sets which are not hit by future peaks. Still, despite some refinement, the arguments are very much based on the above observations.

To formalise ideas, we introduce

$$\Omega_j^n := \mathbb{T}^d \setminus \bigcup_{k=j}^{\infty} \bigcup_{l=M_{k-1}}^{\min\{n, 2K_k M_k\}} \mathcal{I}_k + l\omega, \quad \Omega_j := \bigcap_{n \in \mathbb{N}} \Omega_j^n = \mathbb{T}^d \setminus \bigcup_{k=j}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \mathcal{I}_k + l\omega,$$

where  $j, n \in \mathbb{N}$ . A way to interpret these definitions in terms of our qualitative discussion is the following: by the recursive definition of  $\mathcal{I}_j$  (cf. Section 2.3), the size of the  $M_{j-1}$ -th peak is about  $|\mathcal{I}_j|$ . Hence,  $\Omega_j$  only contains points which are not hit by any peak that appears after  $M_{j-1}$  iterations. Likewise,  $\Omega_j^n$  contains points at which  $\phi_n^+$  might stabilise in finite time, but at which new peaks could still appear at future iterations.

Observe that  $K_k M_k \leq K_0 \kappa^k \cdot 2K_{k-1} M_{k-1} \leq \dots \leq K_0^{k+1} \kappa^{\sum_{i=1}^k l} 2^k M_0$  while  $|\mathcal{I}_k| < \varepsilon_k = c_0 \alpha_0^{-M_{k-1}} \leq c_0 \alpha_0^{-K_0^{k-1} \kappa^{\sum_{i=1}^{k-2} l} 2^{k-1} M_0}$ . Thus, we have  $2K_k M_k \varepsilon_k^d < \varepsilon_k^{d/2}$  for large enough  $k$  and hence,

$$\text{Leb}_{\mathbb{T}^d} \left( \bigcup_{k=j}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \mathcal{I}_k + l\omega \right) < \sum_{k=j}^{\infty} V_d 2K_k M_k \varepsilon_k^d < \sum_{k=j}^{\infty} V_d \varepsilon_k^{d/2}, \quad (3.1)$$

for large enough  $j$ , where  $V_d$  is the normalising factor of the  $d$ -dimensional Lebesgue measure. Thus,  $\text{Leb}_{\mathbb{T}^d}(\Omega_j) > 0$  for large enough  $j \in \mathbb{N}$ .

There might still be points which get hit by infinitely many peaks so that no eventual stabilisation occurs. These are collected within

$$\Omega_\infty := \mathbb{T}^d \setminus \bigcup_{j \in \mathbb{N}} \Omega_j = \bigcap_{i=1}^{\infty} \bigcup_{k=i}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \mathcal{I}_k + l\omega.$$

In the following, we only consider the upper boundary lines  $\phi_n^+$  and the upper bounding graph  $\phi^+$ . All of the results and proofs which are only stated in terms of  $\phi^+$  and  $\phi_n^+$  hold analogously for the lower boundary lines  $\phi_n^-$  and the lower bounding graph  $\phi^-$  as can be seen by considering  $f^{-1}$  instead of  $f$ .

The next proposition is the basis of our geometrical investigation of  $\phi^+$ . Its proof, which is the technical core of this paper, is given in the last section. However, the statement should seem plausible to the reader in the light of the above discussion.

**Proposition 3.1.** *Let  $f \in \mathcal{V}$ . There are  $\lambda > 0$  and  $C > 0$  such that the following is true for sufficiently large  $j$ .*

---

(i) Suppose  $\theta \in \Omega_j^n$  and  $n > 2K_{j-1}M_{j-1} - M_{j-1} - 1$ . Then  $|\phi_n^+(\theta) - \phi_{n-1}^+(\theta)| \leq \alpha^{-\lambda(n-1)}$ .

(ii) Suppose  $\theta, \theta' \in \Omega_j^n$  and  $n \in \mathbb{N}$ . Then  $|\phi_n^+(\theta) - \phi_n^+(\theta')| \leq L_j d(\theta, \theta')$  for some  $L_j \leq \varepsilon_j^{-CK_{j-1}}$  independent of  $n$ .

Now, this information on the geometry of the curves  $\phi_n^+$  allows to determine the Hausdorff dimension of  $\Phi^+$  rather easily (cf. [20]).

**Theorem 3.2.** *Suppose  $f \in \mathcal{V}$ . Then the following statements hold:*

(i)  $D_H(\Phi^+) = d$ ,

(ii)  $\mu_{\phi^+}$  is  $d$ -rectifiable and exact dimensional with  $d_{\mu_{\phi^+}} = d$ .

*Proof.* For each  $j \in \mathbb{N} \cup \{\infty\}$  set  $\psi_j := \phi^+|_{\Omega_j}$ . First, we want to show that the graph  $\Psi_j = \{(\theta, \psi_j(\theta)) : \theta \in \Omega_j\}$  is the image of a bi-Lipschitz continuous function  $g_j$  for all  $j \in \mathbb{N}$ . Define  $g_j : \Omega_j \rightarrow \Omega_j \times X$  via  $\theta \mapsto (\theta, \psi_j(\theta))$  for all  $j \in \mathbb{N} \cup \{\infty\}$ . We have that  $g_j(\Omega_j) = \Psi_j$  and  $d_{\mathbb{T}^d \times X}(g_j(\theta), g_j(\theta')) \geq d(\theta, \theta')$  for all  $\theta, \theta' \in \Omega_j$ . We may assume without loss of generality that  $j$  is large enough<sup>3</sup> so that Proposition 3.1 (ii) yields that  $\phi_n|_{\Omega_j}$  is Lipschitz continuous with Lipschitz constant  $L_j$  independent of  $n$ . Since  $\psi_j = \lim_{n \rightarrow \infty} \phi_n|_{\Omega_j}$ , we also get that  $\psi_j$  is Lipschitz continuous with the same constant and therefore

$$d_{\mathbb{T}^d \times X}(g_j(\theta), g_j(\theta')) \leq (1 + L_j)d(\theta, \theta'),$$

for all  $\theta, \theta' \in \Omega_j$  and  $j \in \mathbb{N}$ . Hence,  $g_j$  is bi-Lipschitz continuous for each  $j \in \mathbb{N}$ .

(i) We want to make use of the fact that the Hausdorff dimension is countably stable, see Lemma 2.4. Because of the bi-Lipschitz continuity, we get that  $D_H(\Psi_j) = D_H(\Omega_j)$ . Since  $\text{Leb}_{\mathbb{T}^d}(\Omega_j) > 0$  for large enough  $j$ , this implies  $D_H(\Psi_j) = d$ . What is left to show is that  $D_H(\Psi_\infty) \leq d$ . Observe that  $\Omega_\infty$  is a lim sup set. With a proper relabelling and doing a similar estimation as in (3.1), we can use Lemma 2.2 to conclude that  $D_H(\Omega_\infty) \leq s$  for all  $s > 0$ . Therefore,  $D_H(\Omega_\infty) = 0$ . Further,  $\Psi_\infty \subset \Omega_\infty \times X$  and hence  $D_H(\Psi_\infty) \leq D_H(\Omega_\infty) + D_B(X) = 1 \leq d$ , applying Theorem 2.6.

(ii) Note that by definition,  $\mu_{\phi^+}$  is absolutely continuous with respect to  $\mathcal{H}^d|_{\Phi^+}$ . We have that  $\mu_{\phi^+}(\Psi_\infty) = 0$  and therefore  $\mu_{\phi^+}$  is also absolutely continuous with respect to  $\mathcal{H}^d|_{\Phi^+ \setminus \Psi_\infty}$ . Since  $\Phi^+ \setminus \Psi_\infty = \bigcup_{j \in \mathbb{N}} \Psi_j$  is a countably  $d$ -rectifiable set—using the observation from the beginning of the proof—we get that  $\mu_{\phi^+}$  is  $d$ -rectifiable, too. Now, by applying Corollary 2.11, we obtain that  $\mu_{\phi^+}$  is exact dimensional with pointwise dimension  $d_{\mu_{\phi^+}} = d$ .  $\square$

*Remark.* By the remark in Section 2.2, we immediately get that the information dimension of  $\mu_{\phi^+}$  equals  $d$ .

---

<sup>3</sup>Observe that for  $j \leq J$ , we have  $\Psi_j \subseteq \Psi_J$  because  $\Omega_j \subseteq \Omega_J$ .

## 4 Minimality and box-counting dimension

For  $n \in \mathbb{N}_0$ , we denote by  $\tilde{\mathcal{I}}_n$  the  $\varepsilon_n/2$ -neighbourhood of  $\mathcal{I}_n$ , that is,  $\tilde{\mathcal{I}}_n := \bigcup_{\theta \in \mathcal{I}_n} B_{\varepsilon_n/2}(\theta)$ , where  $B_r(\theta)$  denotes the open ball of radius  $r$  centred at  $\theta$ . Set

$$\tilde{\Omega}_\infty := \bigcap_{j=1}^{\infty} \bigcup_{k=j}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \tilde{\mathcal{I}}_k + l\omega.$$

**Lemma 4.1.** *Suppose  $\theta \notin \tilde{\Omega}_\infty$ . Then there exists  $j_0 \in \mathbb{N}$  such that for all integers  $j \geq j_0$  we have  $\theta \in \Omega_j$  and*

$$\text{Leb}_{\mathbb{T}^d}(B_{\varepsilon_n/2}(\theta) \cap \Omega_j) / \text{Leb}_{\mathbb{T}^d}(B_{\varepsilon_n/2}(\theta)) \rightarrow 1, \quad (4.1)$$

for  $n \rightarrow \infty$ .

*Proof.* By the assumptions, there is  $j_0 \in \mathbb{N}$  such that  $\theta \notin \bigcup_{k=j_0}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \tilde{\mathcal{I}}_k + l\omega$ . Fix an arbitrary  $j \geq j_0$  and observe that

$$B_{\varepsilon_n/2}(\theta) \cap \left( \bigcup_{k=j}^n \bigcup_{l=M_{k-1}}^{2K_k M_k} \tilde{\mathcal{I}}_k + l\omega \right) = \emptyset$$

for  $n \geq j$  by definition of  $\tilde{\mathcal{I}}_k$ . Thus,

$$B_{\varepsilon_n/2}(\theta) \cap \Omega_j = B_{\varepsilon_n/2}(\theta) \setminus \bigcup_{k=j}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \tilde{\mathcal{I}}_k + l\omega = B_{\varepsilon_n/2}(\theta) \setminus \bigcup_{k=n+1}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \tilde{\mathcal{I}}_k + l\omega.$$

Similarly as in (3.1), we get  $\text{Leb}_{\mathbb{T}^d} \left( \bigcup_{k=n+1}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \tilde{\mathcal{I}}_k + l\omega \right) < \sum_{k=n+1}^{\infty} V_d \varepsilon_k^{d/2}$  for large enough  $n$ , where  $V_d$  normalises the Lebesgue measure.  $\square$

**Lemma 4.2.** *Suppose  $\theta \in \tilde{\Omega}_\infty$ . For each  $\ell \in \mathbb{N}$ , there are arbitrarily large  $j$  such that*

$$B_{\varepsilon_j/2}(\theta) \subseteq \bigcup_{j+1}^{2K_{j+\ell} M_{j+\ell}} \tilde{\mathcal{I}}_{j+\ell} + l\omega \quad (4.2)$$

and

$$\text{Leb}_{\mathbb{T}^d} \left( B_{\varepsilon_j/2}(\theta) \right) - \text{Leb}_{\mathbb{T}^d} \left( B_{\varepsilon_j/2}(\theta) \cap \Omega_{j+1} \right) < \varepsilon_{j+\ell}. \quad (4.3)$$

*Proof.* For  $n \in \mathbb{N}$ , we define

$$j_n := \max \left\{ p \in \mathbb{N}_0 : \exists l \in \left[ M_{p-1}, \min \{ n, 2K_p M_p \} \right] \text{ such that } \theta \in \tilde{\mathcal{I}}_p + l\omega \right\}$$

and let  $l_n \in \left[ M_{j_n-1}, 2K_{j_n} M_{j_n} \right]$  be the corresponding time such that  $\theta \in \tilde{\mathcal{I}}_{j_n} + l_n\omega$ , where uniqueness is guaranteed by  $(\mathcal{F}1)_{j_n}$ . Note that  $j_n$  and  $l_n$  are well-defined for sufficiently large  $n$  and  $j_n \xrightarrow{n \rightarrow \infty} \infty$  because  $\theta \in \tilde{\Omega}_\infty$ .

Further, let  $\theta_* \in \bigcap_{n=0}^{\infty} \mathcal{I}_n$ . Note that  $d(\theta_* + l\omega, \theta) < \frac{3}{2}\varepsilon_{j_n}$  for all  $l$  for which  $\theta \in \tilde{\mathcal{I}}_{j_n} + l\omega$ . Now, suppose there is  $k \in \mathbb{N}$  such that  $\theta \in \tilde{\mathcal{I}}_{j_n} + l_n\omega + k\omega$ . Then

$$d(k\omega, 0) = d(\theta_* + (l_n + k)\omega, \theta_* + l_n\omega) \leq d(\theta_* + (l_n + k)\omega, \theta) + d(\theta, \theta_* + l_n\omega) < 3\varepsilon_{j_n}.$$

As  $\omega$  is Diophantine, this means  $\mathcal{C}|k|^{-\eta} < d(k\omega, 0) < 3\varepsilon_{j_n}$  and hence

$$|k| > \tilde{c}\varepsilon_{j_n}^{-1/\eta}, \quad (4.4)$$

where  $\tilde{c} > 0$ . Define

$$J_n := \max \left\{ N : 2K_N M_N < \tilde{c}\varepsilon_{j_n}^{-1/\eta} \right\}.$$

By (4.4), we have

$$B_{\varepsilon_{j_n}/2}(\theta) \subseteq \Omega_{j_n+1}^{2K_{J_n} M_{J_n}}.$$

Since  $j_n/J_n \xrightarrow{n \rightarrow \infty} 0$ , we have thus shown that for any  $\ell \in \mathbb{N}$  there is arbitrarily large  $j$  such that  $B_{\varepsilon_j/2}(\theta) \subseteq \Omega_{j+1}^{2K_{j+\ell} M_{j+\ell}}$ .

Given  $\ell \in \mathbb{N}$ , assume  $j$  is such that (4.2) holds. Then,

$$B_{\varepsilon_j/2}(\theta) \cap \Omega_{j+1} = B_{\varepsilon_j/2}(\theta) \setminus \bigcup_{k=j+1}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \mathcal{I}_k + l\omega = B_{\varepsilon_j/2}(\theta) \setminus \bigcup_{k=j+\ell+1}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \mathcal{I}_k + l\omega.$$

Finally,  $\text{Leb}_{\mathbb{T}^d} \left( \bigcup_{k=j+\ell+1}^{\infty} \bigcup_{l=M_{k-1}}^{2K_k M_k} \mathcal{I}_k + l\omega \right) < \sum_{k=j+\ell+1}^{\infty} V_d \varepsilon_k^{d/2} < \varepsilon_{j+\ell}$  for large enough  $j$ .  $\square$

**Corollary 4.3.** *Let  $f \in \mathcal{V}$ . If  $\phi = \phi^+$  a.e. and  $\phi$  is an upper semi-continuous invariant graph, then  $\phi = \phi^+$ . In other words,  $\phi^+$  is the unique upper semi-continuous invariant graph in its equivalence class. Further,*

$$\phi^+ \left( \overline{B_r(\theta)} \right) \subseteq \overline{\phi^+(B_r(\theta))}, \quad (4.5)$$

for all  $\theta \in \mathbb{T}^d$  and all  $r > 0$ .

*Proof.* We first show (4.5). Let  $\theta \in \mathbb{T}^d$  and  $r > 0$  be given and let  $\theta_0 \in \partial B_r(\theta) = \overline{B_r(\theta)} \setminus B_r(\theta)$ .

Consider the case where  $\theta_0 \notin \tilde{\Omega}_{\infty}$  and let  $j$  be as in Lemma 4.1. Equation (4.1) yields that for every  $\rho > 0$  there is  $\theta' \in B_r(\theta) \cap B_{\rho}(\theta_0)$  such that  $\theta' \in \Omega_j$ . Without loss of generality we may assume that  $j$  is large enough so that Proposition 3.1(ii) gives

$$|\phi_n^+(\theta_0) - \phi_n^+(\theta')| \leq L_j d(\theta_0, \theta')$$

for arbitrary  $n$  and thus  $|\phi^+(\theta_0) - \phi^+(\theta')| \leq L_j d(\theta_0, \theta') \leq L_j \rho$  as  $\phi_n^+ \rightarrow \phi^+$  point-wise. Sending  $\rho$  to zero proves the statement in the case  $\theta_0 \notin \tilde{\Omega}_{\infty}$ .

Now, suppose  $\theta_0 \in \tilde{\Omega}_{\infty}$  and let  $\delta > 0$ . Lemma 4.2 yields that there is arbitrarily large  $j \in \mathbb{N}$  such that  $\theta_0 \in \Omega_j^{2K_{j+2} M_{j+2}}$ . For sufficiently large  $j$ , equation (4.3) gives  $B_r(\theta) \cap B_{\delta \varepsilon_j^{c_{K_{j-1}}}}(\theta_0) \cap \Omega_j \neq \emptyset$ , where

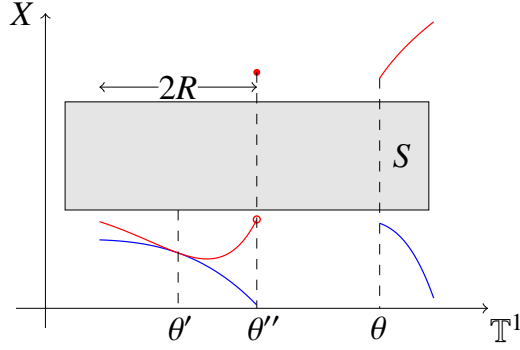


Figure 2: The 1-dimensional case: Assuming a gap within the minimal set implies the existence of a point  $(\theta'', \phi^+(\theta''))$  which is isolated from one side (here, from the left). This contradicts Corollary 4.3.

we may choose  $C$  such that  $L_j \leq \varepsilon_j^{-CK_{j-1}}$  (see Proposition 3.1 (ii)). Let  $\theta' \in B_r(\theta) \cap B_{\frac{r}{\delta \varepsilon_j^{CK_{j-1}}}}(\theta_0) \cap \Omega_j$ . Then  $|\phi_{2K_j M_j}^+(\theta_0) - \phi_{2K_j M_j}^+(\theta')| \leq \delta$  by Proposition 3.1 (ii). Without loss of generality we may further assume that  $j$  is large enough to ensure  $|\phi^+(\theta_0) - \phi_{2K_j M_j}^+(\theta_0)| \leq \delta$  and  $\sum_{k=2K_j M_j}^{\infty} \alpha^{-\lambda k} \leq \delta$ , for  $\lambda$  as in Proposition 3.1(i). This eventually gives

$$|\phi^+(\theta_0) - \phi^+(\theta')| \leq |\phi^+(\theta_0) - \phi_{2K_j M_j}^+(\theta_0)| + |\phi_{2K_j M_j}^+(\theta_0) - \phi_{2K_j M_j}^+(\theta')| + |\phi_{2K_j M_j}^+(\theta') - \phi^+(\theta')| \leq 3\delta,$$

where we used Proposition 3.1(i) (again, assuming large enough  $j$ ) to estimate the last term.

Given arbitrary  $\theta \in \mathbb{T}^d$  and  $r > 0$ , we have thus shown that for each  $\theta_0 \in \partial B_r(\theta)$  there is a sequence  $\theta_n \xrightarrow{n \rightarrow \infty} \theta_0$  within  $B_r(\theta)$  such that  $\phi^+(\theta_0) = \lim_{n \rightarrow \infty} \phi^+(\theta_n)$ . Hence, (4.5) holds. In fact, the construction shows that even if  $\phi = \phi^+$  only *almost* everywhere, we still find a sequence  $\tilde{\theta}_n \xrightarrow{n \rightarrow \infty} \theta_0$  within  $B_r(\theta)$  such that  $\phi(\tilde{\theta}_n) = \phi^+(\tilde{\theta}_n) \xrightarrow{n \rightarrow \infty} \phi^+(\theta_0)$ . Thus, if  $\phi$  is upper semi-continuous, this necessarily yields  $\phi \geq \phi^+$ . On the other hand, if  $\phi$  is invariant, its graph is contained entirely within the maximal invariant set  $\Lambda$  so that  $\phi \leq \phi^+$ . Thus,  $\phi = \phi^+$ .  $\square$

Given an  $f$ -invariant and closed set  $B \subseteq \mathbb{T}^d \times X$ , the associated *upper* and *lower bounding graphs*

$$\phi_B^+(\theta) := \sup\{x : (\theta, x) \in B\} \quad \text{and} \quad \phi_B^-(\theta) := \inf\{x : (\theta, x) \in B\}$$

are invariant graphs, where  $\phi_B^+$  is upper semi-continuous and  $\phi_B^-$  is lower semi-continuous. Vice versa, continuity of  $f$  straightforwardly gives that the topological closure of an invariant graph  $\Phi$  is a closed invariant set. Further, if  $\phi$  is upper (lower) semi-continuous, then it equals the corresponding upper (lower) bounding graph:  $\phi = \phi_{\Phi}^+$  ( $\phi = \phi_{\Phi}^-$ ) (see [25, Corollary 1 & 2]).

*Remark.* For the proof of the next statement, it is important to note that due to the non-zero Lyapunov exponents there is no lower and upper semi-continuous invariant graph that coincides almost everywhere with  $\phi^+$  and  $\phi^-$ , respectively (cf. [22, Lemma 3.2]).



---

**Theorem 4.4.** *Let  $f \in \mathcal{V}$ . Then  $[\phi^-, \phi^+]$  is minimal. As a consequence,  $D_B(\phi^-) = D_B(\phi^+) = d + 1$ .*

*Proof.* As  $\phi^-$  and  $\phi^+$  are lower and upper semi-continuous invariant graphs, respectively,  $[\phi^-, \phi^+]$  is a compact invariant set.

For a contradiction, assume  $[\phi^-, \phi^+]$  is not minimal. Then there is a proper subset  $M \subset [\phi^-, \phi^+]$  which is compact and invariant. Theorem 1.1 ( $\mathcal{N}$ ) and Corollary 4.3 as well as the above remark yield that  $\phi_M^\pm = \phi^\pm$ . Hence, there have to be  $\theta \in \mathbb{T}^d$  and  $x \in (\phi^-(\theta), \phi^+(\theta))$  with  $(\theta, x) \notin M$ . Since  $M$  is compact, there is an open strip  $S := B_{\varepsilon_1}(\theta_0) \times B_{\varepsilon_2}(x_0)$  with  $\varepsilon_1, \varepsilon_2 > 0$  centred at some  $(\theta_0, x_0) \in \mathbb{T}^d \times X$  such that  $(\theta, x) \in S$  and  $S \cap M = \emptyset$ .

By Theorem 1.1, we may assume without loss of generality that there is a pinched point  $\theta' \in B_{\varepsilon_1}(\theta_0)$  with  $\phi^-(\theta') = \phi^+(\theta') \leq x_0 - \varepsilon_2$ . In other words,  $\Phi^-$  and  $\Phi^+$  have a common point below  $S$ . By continuity of  $\phi^+$  at the pinched points (see the remark below Theorem 1.1), we have that  $\Phi^+|_{B_r(\theta')} := \Phi^+ \cap B_r(\theta') \times [0, 1]$  is below  $S$  for all small enough  $r > 0$ . Denote by  $R$  the supremum of all such  $r$  and suppose without loss of generality that  $B_R(\theta') \subseteq B_{\varepsilon_1}(\theta')$ . Then,  $\Phi^+|_{B_R(\theta')}$  is below  $S$ , while  $\Phi^+|_{B_{R+\delta}(\theta')}$  necessarily contains points above  $S$  for each  $\delta > 0$ . Hence, there is  $\theta'' \in \partial B_R(\theta')$  such that  $(\theta'', \phi^+(\theta''))$  is above  $S$ , contradicting Corollary 4.3 (cf. Figure 2). This proves the desired minimality.

As an immediate consequence, we have  $\overline{\phi^-} = \overline{\phi^+} = [\phi^-, \phi^+]$  and so, by the remark in Section 2.1,  $D_B(\phi^-) = D_B(\phi^+) = D_B([\phi^-, \phi^+])$ . Since  $\phi^- < \phi^+$  a.e., we further have  $D_B([\phi^-, \phi^+]) = d + 1$ .  $\square$

## 5 Proof of Proposition 3.1

We now turn to the proof of Proposition 3.1. It is based on both the  $C^2$ -estimates and the dynamical assumptions that define the set  $\widehat{U}_\omega$  (see Section 2.3).

A crucial point is to control the number of times a forward orbit spends in the contracting and a backward orbit spends in the expanding region, respectively. For  $n, N \in \mathbb{N}$  set

$$\begin{aligned} \mathcal{P}_n^N(\theta, x) &:= \#\{l \in [n, N-1] \cap \mathbb{N}_0 : f_\theta^l(x) \in C \text{ and } \theta + l\omega \notin \mathcal{I}_0\}; \\ \mathcal{Q}_n^N(\theta, x) &:= \#\{l \in [n, N-1] \cap \mathbb{N}_0 : f_\theta^{-l}(x) \in E \text{ and } \theta - l\omega \notin \mathcal{I}_0 + \omega\}. \end{aligned}$$

The following combinatorial lemmas are important ingredients for this control. Their proofs can be found in [14]. In the following, it is convenient to set  $M_{-1} := 0$  (as before) and  $\mathcal{I}_{-1} := \mathcal{I}_0$  as well as  $\mathcal{Z}_{-1}^-, \mathcal{Z}_{-1}^+ := \emptyset$ .

**Definition 5.1.**  $(\theta, x)$  verifies  $(\mathcal{B}1)_n$  and  $(\mathcal{B}2)_n$ , respectively if

$$(\mathcal{B}1)_n \quad x \in C \text{ and } \theta \notin \mathcal{Z}_{n-1}^-,$$

$$(\mathcal{B}2)_n \quad x \in E \text{ and } \theta \notin \mathcal{Z}_{n-1}^+.$$

**Lemma 5.2** (cf. [14, Lemma 4.4]). *Let  $f \in \mathcal{V}$ ,  $n \in \mathbb{N}_0$  and assume  $(\theta, x)$  satisfies  $(\mathcal{B}1)_n$ . Let  $\mathcal{L}$  be the first time  $l$  such that  $\theta + l\omega \in \mathcal{I}_n$  and let  $0 < \mathcal{L}_1 < \dots < \mathcal{L}_N = \mathcal{L}$  be all those times  $m \leq \mathcal{L}$*

---

for which  $\theta + m\omega \in \mathcal{I}_{n-1}$ . Then  $f^{\mathcal{L}_i + M_{n-1} + 2}(\theta, x)$  satisfies  $(\mathcal{B}1)_n$  for each  $i = 1, \dots, N-1$  and the following implication holds

$$f_\theta^k(x) \notin C \Rightarrow \theta + k\omega \in \mathcal{V}_{n-1} \text{ and } f_\theta^k(x) \in [0, 1] \quad (k = 1, \dots, \mathcal{L}).$$

Analogously for backwards iteration: Instead of  $(\mathcal{B}1)_n$ , assume  $(\theta, x)$  satisfies  $(\mathcal{B}2)_n$ . Let  $\mathcal{R}$  be the first time  $r$  such that  $\theta - r\omega \in \mathcal{I}_n + \omega$  and let  $0 < \mathcal{R}_1 < \dots < \mathcal{R}_N = \mathcal{R}$  be all those times  $m \leq \mathcal{R}$  for which  $\theta - m\omega \in \mathcal{I}_{n-1}$ . Then  $f^{-\mathcal{R}_i - M_{n-1}}(\theta, x)$  satisfies  $(\mathcal{B}2)_n$  for each  $i = 1, \dots, N-1$  and the following implication holds

$$f_\theta^{-k}(x) \notin E \Rightarrow \theta - k\omega \in \mathcal{W}_{n-1} \text{ and } f_\theta^{-k}(x) \in [0, 1] \quad (k = 1, \dots, \mathcal{R}).$$

**Lemma 5.3** (cf. [14, Lemma 4.8]). Let  $f \in \mathcal{V}$  and assume  $(\theta, x)$  verifies  $(\mathcal{B}1)_n$  for  $n \in \mathbb{N}$ . Let  $0 < \mathcal{L}_1 < \dots < \mathcal{L}_N = \mathcal{L}$  be as in Lemma 5.2. Then, for each  $i = 1, \dots, N$ , we have

$$P_k^{\mathcal{L}_i}(\theta, x) \geq b_n(\mathcal{L}_i - k) \quad (k = 0, \dots, \mathcal{L}_i - 1). \quad (5.1)$$

Analogously, assume  $(\theta, x)$  verifies  $(\mathcal{B}2)_n$  for  $n \in \mathbb{N}$ . Let  $0 < \mathcal{R}_1 < \dots < \mathcal{R}_N = \mathcal{R}$  be as in Lemma 5.2. Then, for each  $i = 1, \dots, N$ , we have

$$Q_k^{\mathcal{R}_i}(\theta, x) \geq b_n(\mathcal{R}_i - k) \quad (k = 1, \dots, \mathcal{R}_i - 1).$$

As before, we consider the iterated upper boundary lines only. Given fixed  $n \in \mathbb{N}$  and  $\theta \in \mathbb{T}^d$ , we set

$$\theta_k := \theta - (n - k)\omega \quad \text{and} \quad x_k := f_{\theta_0}^k(1)$$

such that  $\phi_k^+(\theta_k) = x_k$ .

Let  $p \in \mathbb{N}$  and consider a finite orbit  $\{(\theta_0, x), \dots, f^n(\theta_0, x)\}$  which initially verifies  $(\mathcal{B}1)_p$  and hits  $\mathcal{I}_p$  only at  $\theta_0 + n\omega$ . Lemma 5.3 provides us with a lower bound on the times spent in the contracting region between any time  $k$  and only such following times at which the orbit hits  $\mathcal{I}_{p-1}$ . If we want a lower bound on the times in the contracting region between any two consecutive moments  $k < l$ , we have to deal with the fact that Lemma 5.2 might allow the orbit to stay in the expanding region for  $M_{p-1} + 1$  times after hitting  $\mathcal{I}_{p-1}$ . This is taken care of in the following corollary of Lemma 5.2 and Lemma 5.3.

For  $\theta \in \mathbb{T}^d$  and  $0 \leq k \leq n$ , set

$$p_k^n(\theta) = \max \left\{ p \in \mathbb{N}_0 : \exists l \in \left[ M_{p-1}, \min \{ n, n - k + M_p + 1 \} \right] \text{ such that } \theta - l\omega \in \mathcal{I}_p \right\}$$

with  $\max \emptyset := -1$ . At times, the following (and obviously equivalent) characterisation of  $p_k^n(\theta)$  is useful

$$p_k^n(\theta) = \max \left\{ p \in \mathbb{N}_0 : \exists l \in \left[ \max \{ 0, k - M_p - 1 \}, n - M_{p-1} \right] \text{ such that } \theta_l \in \mathcal{I}_p \right\}.$$

Observe that  $p_k^n(\theta)$  and  $p_{k-\ell}^{n-\ell}(\theta)$  are non-increasing in  $\ell$ .

---

**Corollary 5.4.** *Let  $f \in \mathcal{V}$  and suppose  $(\theta_0, x) = (\theta - n\omega, x)$  satisfies  $(\mathcal{B}1)_{p_0^n(\theta)+1}$ . Then*

$$\mathcal{P}_k^n(\theta_0, x) \geq b_{p_k^n(\theta)+1} \left( n - k - \sum_{j=0}^{p_k^n(\theta)} (M_j + 2) \right) \quad \text{for each } k = 0, \dots, n-1. \quad (5.2)$$

*Proof.* For integers  $p \geq -1$ , set

$$\Theta_p := \left\{ (\theta, x, n) \in \mathbb{T}^d \times [c, 1] \times \mathbb{N} : p_0^n(\theta) \leq p \text{ and } (\theta - n\omega, x) \text{ satisfy } (\mathcal{B}1)_{p_0^n(\theta)+1} \right\}.$$

We say (5.2) holds within  $\Theta_p$  if (5.2) is true for all  $(\theta, x, n) \in \Theta_p$ . We show by induction on  $p$  that (5.2) holds within  $\Theta_p$  for all  $p$ . Note that within  $\Theta_{-1}$  (5.2) follows directly from (2.1).

Suppose there is an integer  $p_0 \geq -1$  so that (5.2) holds within  $\Theta_{p_0}$ . Set  $p = p_0 + 1$  and fix  $(\theta, x, n) \in \Theta_p \setminus \Theta_{p_0}$  which is assumed to be non-empty without loss of generality. Let  $\mathcal{L}$  be the largest positive integer not bigger than  $n - M_{p-1}$  such that  $\theta_{\mathcal{L}} \in \mathcal{I}_p$  and assume without loss of generality that  $\mathcal{L} < n$ . Note that  $p_{\mathcal{L}}^n(\theta) = p$ . First, let  $k \in [\mathcal{L}, n-1]$ . There are two cases to be considered.

- (a) Suppose  $\mathcal{L} > n - M_p - 2$ . Then  $\mathcal{L} \in [\max\{0, k - M_p - 1\}, n - M_{p-1}]$  for all  $k \leq n-1$ , by definition of  $\mathcal{L}$ . Hence,  $p_k^n(\theta) = p$  for all  $k \in [\mathcal{L}, n-1]$  since  $\theta_{\mathcal{L}} \in \mathcal{I}_p$ . Thus,  $k \geq \mathcal{L} > n - M_{p_k^n(\theta)} - 2$  and so  $M_{p_k^n(\theta)} > n - k - 2$  so that (5.2) holds trivially.
- (b) Suppose  $\mathcal{L} \leq n - M_p - 2$ . Without loss of generality, we may assume  $n > \mathcal{L} + M_p + 2$ . First, consider  $k \geq \mathcal{L} + M_p + 2$ . Then  $p_k^n(\theta) < p$  and hence  $p_{k-(\mathcal{L}+M_p+2)}^{n-(\mathcal{L}+M_p+2)}(\theta) \leq p_k^n(\theta) < p$ . Further by Lemma 5.2,  $f^{\mathcal{L}+M_p+2}(\theta_0, x)$  satisfies  $(\mathcal{B}1)_{p+1}$ , and thus  $(\mathcal{B}1)_{p_0+1}$ . Hence, we get

$$\begin{aligned} \mathcal{P}_k^n(\theta_0, x) &= \mathcal{P}_{k-(\mathcal{L}+M_p+2)}^{n-(\mathcal{L}+M_p+2)}(f^{\mathcal{L}+M_p+2}(\theta_0, x)) \geq b_{p_{k-(\mathcal{L}+M_p+2)}^{n-(\mathcal{L}+M_p+2)}(\theta)+1} \left( n - k - \sum_{j=0}^{p_{k-(\mathcal{L}+M_p+2)}^{n-(\mathcal{L}+M_p+2)}(\theta)} (M_j + 2) \right) \\ &\geq b_{p_k^n(\theta)+1} \left( n - k - \sum_{j=0}^{p_k^n(\theta)} (M_j + 2) \right), \end{aligned}$$

where the first estimate follows by the induction hypothesis and the last estimate from the fact that  $b_q$  is decreasing in  $q$ . Now, if  $k \in [\mathcal{L}, \mathcal{L} + M_p + 1]$ , then

$$\begin{aligned} \mathcal{P}_k^n(\theta_0, x) &= \mathcal{P}_k^{\mathcal{L}+M_p+2}(\theta_0, x) + \mathcal{P}_{\mathcal{L}+M_p+2}^n(\theta_0, x) \geq \mathcal{P}_{\mathcal{L}+M_p+2}^n(\theta_0, x) \\ &\geq b_{p_{\mathcal{L}+M_p+2}^n(\theta)+1} \left( n - \mathcal{L} - M_p - 2 - \sum_{j=0}^{p_{\mathcal{L}+M_p+2}^n(\theta)} (M_j + 2) \right) \\ &\geq b_{p_k^n(\theta)+1} \left( n - k - M_p - 2 - \sum_{j=0}^{p_{\mathcal{L}+M_p+2}^n(\theta)} (M_j + 2) \right) \geq b_{p_k^n(\theta)+1} \left( n - k - \sum_{j=0}^{p_k^n(\theta)} (M_j + 2) \right), \end{aligned}$$

where the last estimate holds since  $p_k^n(\theta) = p$  for  $k \leq \mathcal{L} + M_p + 1$ .

We have thus shown

$$\mathcal{P}_k^n(\theta_0, x) \geq b_{p_k^n(\theta)+1} \left( n - k - \sum_{j=0}^{p_k^n(\theta)} (M_j + 2) \right) \quad (5.3)$$

for  $k \in [\mathcal{L}, n-1]$ .

It remains to consider  $k < \mathcal{L}$ . Since  $p_k^n(\theta) \geq p_{\mathcal{L}}^n(\theta) = p$ , we obtain

$$\begin{aligned} \mathcal{P}_k^n(\theta_0, x) &= \mathcal{P}_k^{\mathcal{L}}(\theta_0, x) + \mathcal{P}_{\mathcal{L}}^n(\theta_0, x) \geq b_{p+1}(\mathcal{L} - k) + b_{p_{\mathcal{L}}^n(\theta)+1} \left( n - \mathcal{L} - \sum_{j=0}^{p_{\mathcal{L}}^n(\theta)} M_j + 2 \right) \\ &\geq b_{p+1} \left( n - k - \sum_{j=0}^p M_j + 2 \right), \end{aligned}$$

where we used equation (5.1) and (5.3) in the first estimate. As  $(\theta, x, n)$  was arbitrary in  $\Theta_p \setminus \Theta_{p_0}$ , this shows that (5.2) holds within  $\Theta_p$ .  $\square$

For  $k, n \in \mathbb{N}$ , set  $i_k^n := \max\{l : n - k \geq 2K_l M_l - M_l - 1\}$ .

**Proposition 5.5.** *Suppose  $\theta \in \Omega_j^n$  for some  $j \in \mathbb{N}$ . Then  $i_k^n \geq p_k^n(\theta)$  for all  $0 \leq k \leq n - (2K_{j-1} M_{j-1} - M_{j-1} - 1)$ .*

*Proof.* Note that by the assumptions  $i_k^n \geq j - 1$ . Thus, without loss of generality we may assume  $p_k^n(\theta) > j - 1$ . By definition of  $p_k^n(\theta)$ , there is  $l \in [M_{p_k^n(\theta)-1}, n - k + M_{p_k^n(\theta)} + 1]$  such that  $\theta - l\omega \in \mathcal{I}_{p_k^n(\theta)}$ . Since  $\theta \in \Omega_j^n$ , this implies  $l > 2K_{p_k^n(\theta)} M_{p_k^n(\theta)}$  and thus,  $n - k > 2K_{p_k^n(\theta)} M_{p_k^n(\theta)} - M_{p_k^n(\theta)} - 1$  which means  $i_k^n \geq p_k^n(\theta)$ .  $\square$

*Proof of Proposition 3.1.* Let  $\theta \in \Omega_j^n$  and let  $\mathcal{L}$  be the smallest positive integer such that  $\theta_0 - \mathcal{L}\omega = \theta - (\mathcal{L} + n)\omega \in \mathcal{I}_{p_n^n(\theta)}$ . Then  $(\theta_0 - (\mathcal{L} - 1)\omega, 1)$  satisfies  $(\mathcal{B}1)_{p_n^n(\theta)+1}$  because of  $(\mathcal{F}1)_{p_n^n(\theta)}$ . By (1.2) and by the monotonicity (1.3) of the fibre maps, we have the implication

$$f_{\theta_0 - (\mathcal{L}-1)\omega}^{\mathcal{L}-1+k}(1) \in C \implies f_{\theta_0}^k(1) \in C,$$

for all  $k \geq 0$ . Further, we observe that  $p_0^n(\theta) = p_{\mathcal{L}-1}^{\mathcal{L}-1+n}(\theta)$  and actually  $p_k^n(\theta) = p_{\mathcal{L}-1+k}^{\mathcal{L}-1+n}(\theta)$  for all  $k = 0, \dots, n$ . By Corollary 5.4, we thus get

$$\begin{aligned} \mathcal{P}_k^n(\theta_0, 1) &\geq \mathcal{P}_{\mathcal{L}-1+k}^{\mathcal{L}-1+n}(\theta_0 - (\mathcal{L} - 1)\omega, 1) \geq b_{p_k^n(\theta)+1} \left( n - k - \sum_{\ell=0}^{p_k^n(\theta)} (M_\ell + 2) \right) \\ &\stackrel{\text{Proposition 5.5}}{\geq} b_{i_k^n+1} \left( n - k - \sum_{\ell=0}^{i_k^n} (M_\ell + 2) \right), \end{aligned} \quad (5.4)$$

for  $0 \leq k \leq n - (2K_{j-1}M_{j-1} - M_{j-1} - 1)$ . Now, note that  $\sum_{\ell=0}^{i_k^n} (M_\ell + 2) \leq 3/2M_{i_k^n}$  for large enough  $i_k^n$  (and hence, for large enough  $j$  since  $i_k^n \geq j - 1$ ). Further,  $(n - k)/K_{i_k^n} \geq 2M_{i_k^n} - M_{i_k^n}/K_{i_k^n} - 1/K_{i_k^n}$  by definition of  $i_k^n$ . Thus for large enough  $j$ , we have  $\sum_{\ell=0}^{i_k^n} (M_\ell + 2) \leq (n - k)/K_{i_k^n}$  and so by (5.4)

$$\mathcal{P}_k^n(\theta_0, 1) \geq b_{i_k^n+1}(1 - 1/K_{i_k^n})(n - k) \geq b^2(n - k). \quad (5.5)$$

We hence have

$$\begin{aligned} & |\phi_n^+(\theta) - \phi_{n-1}^+(\theta)| \\ &= \phi_{n-1}^+(\theta) - \phi_n^+(\theta) = (\phi_0^+(\theta_1) - \phi_1^+(\theta_1)) \cdot \prod_{k=1}^{n-1} \frac{\phi_k^+(\theta_{k+1}) - \phi_{k+1}^+(\theta_{k+1})}{\phi_{k-1}^+(\theta_k) - \phi_k^+(\theta_k)} \\ &\leq \prod_{k=1}^{n-1} \frac{f_{\theta_k}(\phi_{k-1}^+(\theta_k)) - f_{\theta_k}(\phi_k^+(\theta_k))}{\phi_{k-1}^+(\theta_k) - \phi_k^+(\theta_k)} \leq \alpha^{p((n-1)-\mathcal{P}_1^n(\theta_0, 1)) - 2\mathcal{P}_1^n(\theta_0, 1)/p} \\ &\stackrel{(5.5)}{\leq} \alpha^{p(1-b^2-2b^2/p)(n-1)}, \end{aligned}$$

where we assumed—without loss of generality—that  $\phi_{k-1}^+(\theta_k) - \phi_k^+(\theta_k) > 0$  for all  $k \in \{1, \dots, n\}$ . This proves the first part with  $\lambda = 2b^2/p - p(1 - b^2) > 0$ .

Let  $\varphi_k^n(\theta, \theta') := \#\{\ell \in [k, n - 1] \cap \mathbb{N}_0 : x_\ell, x'_\ell \in C\}$  for  $\theta, \theta' \in \mathbb{T}^d$ . By induction on  $n$ , we first show that for all  $n \in \mathbb{N}$

$$|\phi_n^+(\theta) - \phi_n^+(\theta')| \leq Sd(\theta, \theta') \sum_{k=1}^n \alpha^{p(n-k-\varphi_k^n(\theta, \theta')) - 2\varphi_k^n(\theta, \theta')/p}. \quad (5.6)$$

For  $n = 1$ , this is equation (2.3). Suppose (5.6) holds for some  $n \in \mathbb{N}$ . Since  $\varphi_k^n(\theta - \omega, \theta' - \omega) + \varphi_n^{n+1}(\theta, \theta') = \varphi_n^{n+1}(\theta, \theta')$ , this yields

$$\begin{aligned} & |\phi_{n+1}^+(\theta) - \phi_{n+1}^+(\theta')| = |f_{\theta-\omega}(\phi_n^+(\theta - \omega)) - f_{\theta'-\omega}(\phi_n^+(\theta' - \omega))| \\ &\leq \alpha^{p(1-\varphi_n^{n+1}(\theta, \theta')) - \frac{2}{p}\varphi_n^{n+1}(\theta, \theta')} |\phi_n^+(\theta - \omega) - \phi_n^+(\theta' - \omega)| + Sd(\theta - \omega, \theta' - \omega) \\ &\leq Sd(\theta, \theta') \sum_{k=1}^{n+1} \alpha^{p(n+1-k-\varphi_k^{n+1}(\theta, \theta')) - 2\varphi_k^{n+1}(\theta, \theta')/p} \end{aligned}$$

where we used (2.2)–(2.4) in the first estimate and the induction hypothesis in the last step. Hence, equation (5.6) holds.

Now, consider sufficiently large  $j$  and suppose  $\theta, \theta' \in \Omega_j^n$ . Suppose  $n > 2K_{j-1}M_{j-1} - M_{j-1} - 1$  and observe that equation (5.5) gives

$$\varphi_k^n(\theta, \theta') \geq n - k - (2(n - k) - \mathcal{P}_k^n(\theta) - \mathcal{P}_k^n(\theta')) \geq n - k - 2(1 - b^2)(n - k) = (2b^2 - 1)(n - k)$$

for all  $k = 0, \dots, n - (2K_{j-1}M_{j-1} - M_{j-1} - 1)$ . Plugging this into (5.6) yields

$$\begin{aligned} & |\phi_n^+(\theta) - \phi_n^+(\theta')| \\ & \leq Sd(\theta, \theta') \left( \sum_{k=1}^{n-2K_{j-1}M_{j-1}-M_{j-1}-1} \alpha^{(2p(1-b^2)-2(2b^2-1)/p)(n-k)} + \sum_{k=n-2K_{j-1}M_{j-1}-M_{j-1}}^n \alpha^{p(n-k-\varphi_k^n(\theta, \theta'))-2\varphi_k^n(\theta, \theta')/p} \right) \\ & \leq L_j d(\theta, \theta'), \end{aligned}$$

where  $L_j := S \cdot \left( \sum_{l=2K_{j-1}M_{j-1}-M_{j-1}-1}^{\infty} \alpha^{(2p(1-b^2)-2(2b^2-1)/p)l} + \sum_{l=0}^{2K_{j-1}M_{j-1}-M_{j-1}} \alpha^{pl} \right)$ . It is immediate that  $|\phi_n^+(\theta) - \phi_n^+(\theta')| \leq L_j d(\theta, \theta')$  holds for  $n \leq 2K_{j-1}M_{j-1} - M_{j-1} - 1$ , too. Finally, observe that there is  $C > 0$  (independent of  $j$ ) such that  $L_j \leq \varepsilon_j^{-CK_{j-1}}$  for large enough  $j$ .  $\square$

## References

- [1] C. Grebogi, E. Ott, S. Pelikan, and J.A. Yorke. Strange attractors that are not chaotic. *Physica D*, 13:261–268, 1984.
- [2] G. Keller. A note on strange nonchaotic attractors. *Fundam. Math.*, 151(2):139–148, 1996.
- [3] R. Bowen. Entropy for group endomorphisms and homogeneous spaces. *Trans. Amer. Math. Soc.*, 153:401–414, 1971.
- [4] P. Glendinning, T. Jäger, and J. Stark. Strangely dispersed minimal sets in the quasiperiodically forced Arnold circle map. *Nonlinearity*, 22(4):835–854, 2009.
- [5] P. Glendinning. Global attractors of pinched skew products. *Dyn. Syst.*, 17:287–294, 2002.
- [6] F.J. Romeiras, A. Bondeson, E. Ott, T.M. Antonsen Jr., and C. Grebogi. Quasiperiodically forced dynamical systems with strange nonchaotic attractors. *Physica D*, 26:277–294, 1987.
- [7] U. Feudel, J. Kurths, and A. Pikovsky. Strange nonchaotic attractor in a quasiperiodically forced circle map. *Physica D*, 88:176–186, 1995.
- [8] W.L. Ditto, M.L. Spano, H.T. Savage, S.N. Heagy, J. Rauseo, and E. Ott. Experimental observation of a strange nonchaotic attractor. *Phys. Rev. Lett.*, 65(5):533–536, 1990.
- [9] W.L. Ditto, S. Rauseo, R. Cawley, C. Grebogi, G.-H. Hsu, E. Kostelich, E. Ott, H.T. Savage, R. Segnan, M.L. Spano, and J.A. Yorke. Experimental observation of crisis-induced intermittency and its critical exponents. *Phys. Rev. Lett.*, 63(9):923–926, 1989.
- [10] L.-S. Young. Lyapunov exponents for some quasi-periodic cocycles. *Ergodic Theory Dynam. Systems*, 17:483–504, 1997.
- [11] K. Bjerklöv. Positive Lyapunov exponent and minimality for a class of one-dimensional quasi-periodic Schrödinger equations. *Ergodic Theory Dynam. Systems*, 25:1015–1045, 2005.

- 
- [12] Kristian Bjerklöv. SNA's in the quasi-periodic quadratic family. *Comm. Math. Phys.*, 286(1):137–161, 2009.
- [13] T. Jäger. Strange non-chaotic attractors in quasiperiodically forced circle maps. *Comm. Math. Phys.*, 289(1):253–289, 2009.
- [14] G. Fuhrmann. Non-smooth saddle-node bifurcations I: existence of an SNA. *Ergodic Theory Dynam. Systems*, FirstView:1–26, 12 2014.
- [15] J.F. Heagy and S.M. Hammel. The birth of strange nonchaotic attractors. *Physica D*, 70:140–153, 1994.
- [16] A. Prasad, S.S. Negi, and R. Ramaswamy. Strange nonchaotic attractors. *Int. J. Bif. Chaos*, 11(2):291–309, 2001.
- [17] V. Anagnostopoulou and T. Jäger. Nonautonomous saddle-node bifurcations: random and deterministic forcing. *J. Differ. Equations*, 253(2):379–399, 2012.
- [18] M. Ding, C. Grebogi, and E. Ott. Dimensions of strange nonchaotic attractors. *Phys. Lett. A*, 137(4-5):167–172, 1989.
- [19] T. Jäger. On the structure of strange nonchaotic attractors in pinched skew products. *Ergodic Theory Dynam. Systems*, 27:493–510, 2007.
- [20] M. Gröger and T. Jäger. Dimensions of attractors in pinched skew products. *Comm. Math. Phys.*, 320(1):101–119, 2013.
- [21] C. Núñez and R. Obaya. A non-autonomous bifurcation theory for deterministic scalar differential equations. *Discrete and Continuous Dynamical Systems - Series B*, 9:701 – 730, 2008.
- [22] T. Jäger. Quasiperiodically forced interval maps with negative Schwarzian derivative. *Nonlinearity*, 16(4):1239–1255, 2003.
- [23] J. Stark and R. Sturman. Semi-uniform ergodic theorems and applications to forced systems. *Nonlinearity*, 13(1):113–143, 2000.
- [24] J. Milnor. On the concept of attractor. *Comm. Math. Phys.*, 99:177–195, 1985.
- [25] J. Stark. Transitive sets for quasi-periodically forced monotone maps. *Dyn. Syst.*, 18(4):351 – 364, 2003.
- [26] M. Herman. Une méthode pour minorer les exposants de Lyapunov et quelques exemples montrant le caractère local d'un théorème d'Arnold et de Moser sur le tore de dimension 2. *Comment. Math. Helv.*, 58:453–502, 1983.
- [27] K. Bjerklöv. Dynamics of the quasiperiodic Schrödinger cocycle at the lowest energy in the spectrum. *Comm. Math. Phys.*, 272:397–442, 2005.

- 
- [28] Ya.B. Pesin. *Dimension Theory in Dynamical Systems*. Chicago Lectures in Mathematics. University of Chicago Press, 1997.
- [29] J.D. Howroyd. On Hausdorff and packing dimension of product spaces. *Math. Proc. Cambridge Philos. Soc.*, 119(4):715–727, 1996.
- [30] L. Ambrosio and B. Kirchheim. Rectifiable sets in metric and Banach spaces. *Math. Ann.*, 318(3):527–555, 2000.
- [31] O. Zindulka. Hentschel-Procaccia spectra in separable metric spaces. *Real Analysis Exchange*, Summer Symposium in Real Analysis XXVI.:115–119, 2002. See also unpublished note on <http://mat.fsv.cvut.cz/zindulka/>.
- [32] L.S. Young. Dimension, entropy and lyapunov exponents. *Ergodic Theory Dynam. Systems*, 2(1):109–124, 1982.
- [33] Ya.B. Pesin. On rigorous mathematical definitions of correlation dimension and generalized spectrum for dimensions. *J. Stat. Phys.*, 71(3-4):529–547, May 1993.